

voltando atrás:

$$\begin{aligned} \text{rot } \vec{r} &= f(\rho) 2\vec{c} + \frac{df}{d\rho} \frac{(\vec{c} \wedge \vec{r}) \wedge \vec{c}}{\rho} \wedge (\vec{c} \wedge \vec{r}) = 0 \\ &= 2f \cdot \vec{c} + \frac{1}{\rho} \frac{df}{d\rho} \left\{ (\vec{c} \wedge \vec{r})^2 \vec{c} - [(\vec{c} \wedge \vec{r}) \times \vec{c}] (\vec{c} \wedge \vec{r}) \right\} \\ &= 2f \cdot \vec{c} + \rho \frac{df}{d\rho} \vec{c} = 0 \quad \vec{c} \neq 0 \rightarrow \end{aligned}$$

$$2f + \rho \frac{df}{d\rho} = 0 \rightarrow \frac{df}{f} = -\frac{2d\rho}{\rho}$$

$$\int \frac{df}{f} = \int -\frac{2d\rho}{\rho} \rightarrow \boxed{f(\rho) = \frac{k}{\rho^2}} \text{ sendo } k \text{ const.}$$

arbitraria.

Aplicações de divergente:

Determinar $\rho(\vec{r})$ para que
 $\text{div } \rho(\vec{r}) \vec{r} = 0 \quad \vec{r} = P - O$

$$r = |P - O|$$

$$\text{div } \rho(\vec{r}) \vec{r} = \rho \text{ div } \vec{r} + \text{grad } \rho \times \vec{r}$$

$$\text{grad } \rho(\vec{r}) = \frac{d\rho}{dr} \text{grad } r$$

$$\text{grad } |\vec{r}| = \left(\lim_{h \rightarrow 0} \frac{h}{h} \right) \frac{\vec{r}}{r} = \frac{\vec{r}}{r}$$

$$\boxed{\text{div } \vec{r} = I_1 \left(\frac{d\vec{r}}{dP} \right)}$$

sendo

$$I_1(\sigma) = (\vec{i} \times \sigma \vec{i} + \vec{j} \times \sigma \vec{j} + \vec{k} \times \sigma \vec{k}),$$

no caso $I_1(\sigma) = 3$ e $\text{div } \vec{r} = 3$



donde: $\text{div } \rho(\vec{r}) \vec{r} = 3\rho(\vec{r}) + \frac{d\rho}{dr} \frac{\vec{r}}{r} \times \vec{r} = 0$

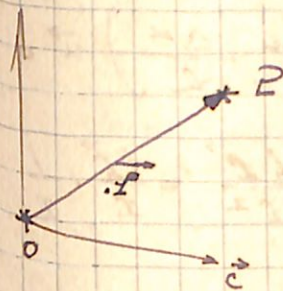
$$3\rho + r \frac{d\rho}{dr} = 0 \quad (\text{integrando})$$

$$\boxed{\rho = \frac{k}{R^3}}$$

19.8.46.

Cálculo de divergente:

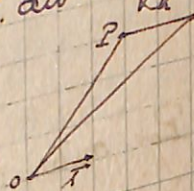
$$\text{div } \vec{c} \wedge (\vec{r} \wedge \vec{c}) \quad \begin{array}{l} |\vec{c}| = c^2 \\ d\vec{c} = 0 \\ \vec{r} = P - O. \end{array}$$



$$\vec{c} \wedge (\vec{r} \wedge \vec{c}) = (\vec{c} \times \vec{c}) \vec{r} - (\vec{c} \times \vec{r}) \vec{c}$$

$$\text{div}(\dots) = \text{div } c^2 \vec{r} - \text{div}(\vec{c} \times \vec{r}) \vec{c}$$

$$= c^2 \text{div } \vec{r} - \vec{c} \times \vec{r} \cdot \text{div } \vec{c} - \frac{\text{grad } c^2 \cdot \vec{r}}{r^2}$$



$$\text{div } \vec{r} = I_1 \left(\frac{d\vec{r}}{dP} \right)$$

$$\frac{d\vec{r}}{dP} \cdot \vec{r} = \lim_{h \rightarrow 0} \frac{h\vec{r}}{h} = \vec{r}$$

No caso, $d\vec{r}/dP = 1$

$$\text{div } \vec{r} = I_1 = \frac{(\vec{c} \times \sigma \vec{i} + \vec{j} \times \sigma \vec{j} + \vec{k} \times \sigma \vec{k})}{\sigma} = 3$$

$$c^2 \text{div } \vec{r} = 3c^2$$

$$\vec{c} \times \vec{r} \cdot \text{div } \vec{c} = 0 \quad \text{pois } \text{div } c^2 = 0$$

$\text{grad}(\vec{c} \times \vec{r})$ podemos desenvolver o produto escalar ou aplicar a definição de grad.

$$\begin{aligned} \text{grad}(\vec{c} \times \vec{r}) &= \text{grad} r \cdot \cos \alpha + r \text{grad} \cos \alpha + \\ &+ \cos \alpha \text{grad} r = \\ &= \frac{\cos \alpha}{r} \vec{r} + r \text{grad} \cos \alpha = \frac{\cos \alpha}{r} \vec{r} - \frac{r \cdot \text{sen} \alpha}{r^2} \vec{r} \end{aligned}$$

$$\vec{n} = \frac{i \vec{r}}{r} \quad (i = \text{operador vetorial})$$

$$\text{grad} \alpha = \left(\frac{d\alpha}{dP} \frac{i \vec{r}}{r} \right) i \frac{\vec{r}}{r}$$

$$\frac{d\alpha}{dP} = \lim_{h \rightarrow 0} \frac{\Delta \alpha}{h} = \left(\frac{\arctg \frac{h}{r}}{h} \right) \vec{u} = \left(\lim_{h \rightarrow 0} \frac{\Delta \alpha}{h} \right) \vec{u} =$$

$$= \left(\lim_{h \rightarrow 0} \frac{\Delta \alpha}{r \text{tg} \Delta \alpha} \right) \vec{n} = \frac{\vec{n}}{r} = \frac{i \vec{r}}{r^2} = \frac{i \vec{r}}{r} \cdot \frac{1}{r}$$

$$\begin{aligned} \text{grad}(\vec{c} \times \vec{r}) &= \frac{\vec{r}}{r} (\cos \alpha \cdot i \text{sen} \alpha) = \\ &= \frac{\vec{r}}{r} e^{-i\alpha} = \vec{c} \end{aligned}$$

Por outro lado, $df = \text{grad} f \times d\vec{l}$

$$\text{grad}(\vec{c} \times \vec{r}) \times d\vec{l} = \vec{c} \times d\vec{l}$$

$$\text{grad}(\vec{c} \times \vec{r}) = \vec{c}$$

finalmente -

$$\text{div} \vec{c} \wedge (\vec{r} \wedge \vec{c}) =$$

$$= 3|\vec{c}|^2 - |\vec{c}|^2 = 2|\vec{c}|^2$$

$$\left. \begin{array}{l} \text{operadores} \\ \text{simples.} \end{array} \right\} \begin{aligned} \text{grad } f(P) &= \vec{v} \\ \text{rot. } \vec{u}(P) &= \vec{w} \\ \text{div. } \vec{u}(P) &= \varphi(P) \quad (\text{se for nula, o campo} \\ &\quad \text{é solenoidal}) \end{aligned}$$

Operadores Superpostos

$$\text{rot. grad } f(P) = 2 \nabla \left(\frac{d \text{grad } f(P)}{dP} \right)$$

O Laplaciano é uma aplicação destes operadores:

$$\nabla^2 f(P) = \text{div. grad } f(P)$$

índice (2) para indicar f. o operador é de segunda ordem.

Comarquemano (!?!):

$$\Delta^1 \vec{u}(P) = \text{grad div } \vec{u} - \text{rot. rot } \vec{u}$$

Determinar $f(P)$ de maneira que:

$$\Delta^2 f(P) = 0 \quad (\text{função harmônica da física})$$

$$P = |\vec{c} \wedge \vec{r}| \quad |\vec{c}| = 1 \quad d\vec{c} = 0 \quad \vec{r} = P - O$$

26.8.46. falta exerc. sobre Δ^2 (Lapl.)

$$\text{Calcular: } \Delta^1 \left(\frac{\vec{c} \wedge \vec{r}}{r \times r} \right) \wedge \vec{r}$$

$$\begin{aligned} |\vec{c}| &= 1 = \text{fixo} \\ \vec{r} &= P - O \end{aligned}$$

$$\text{Façamos } \vec{r} \times \vec{r} = r^2$$

Das combinações possíveis por operadores simples:

- 1) grad rot
- 2) div grad
- 3) div rot
- 4) rot rot
- 5) rot grad
- 6) grad grad
- 7) div div

$$\text{Dadas, } \begin{cases} \text{div. rot} = 0 \\ \text{rot. grad} = 0 \end{cases}$$

Restam tres tiram-pe:

$$\Delta_2 = \text{div. grad.} \quad (\text{aplicado a campo escalar})$$

$$\Delta_2' = \text{grad div} - \text{rot. rot} \quad (\text{aplicado a campo vetorial})$$

$$\Delta_2' \left(\frac{\vec{c} \wedge \vec{r}}{r^2} \right) = \text{grad div} \left(\frac{\vec{c} \wedge \vec{r}}{r^2} \right) - \text{rot rot} \left(\frac{\vec{c} \wedge \vec{r}}{r^2} \right)$$

$$\text{div} \left(\frac{\vec{c} \wedge \vec{r}}{r^2} \right) = \frac{1}{r^2} \text{div} (\vec{c} \wedge \vec{r}) + \left(\text{grad} \frac{1}{r^2} \right) \cdot (\vec{c} \wedge \vec{r})$$

$$\text{div} (\vec{c} \wedge \vec{r}) = (\vec{c} \wedge \vec{r}) \times \text{rot } \vec{r} + \vec{r} \times \text{rot} (\vec{c} \wedge \vec{r})$$

$$(\text{rot } \vec{c} \wedge \vec{r} = 2\vec{c}) \quad (\text{rot } \vec{r} = 0)$$

$$= \vec{r} \times 2\vec{c}$$

$$\text{grad} \frac{1}{r^2} = -\frac{2}{r^3} \text{grad } r = -\frac{2}{r^4} \vec{r}$$

$$\text{então: } \text{div} \left(\frac{\vec{c} \wedge \vec{r}}{r^2} \right) = \frac{2\vec{c} \times \vec{r}}{r^2} - \frac{2}{r^4} \vec{r}$$

$$\text{grad} \frac{2\vec{c} \times \vec{r}}{r^2} = 2 \left[\frac{1}{r^2} \text{grad} \vec{c} \times \vec{r} + \vec{c} \times \vec{r} \text{ grad} \frac{1}{r^2} \right]$$

$$= 2 \left[\frac{\vec{c}}{r^2} - \frac{2\vec{c} \times \vec{r} \cdot \vec{r}}{r^4} \right] \quad (1^a \text{ parcela de } \Delta_2')$$

Passemos ao rotacional:

$$\text{rot} \left(\frac{\vec{c} \wedge \vec{r}}{r^2} \right)$$

$$\text{Pela 3a prop.: } (\text{rot } f \vec{u})$$

$$= \frac{1}{r^2} \text{rot} [(\vec{c} \wedge \vec{r}) \wedge \vec{r}] + \text{grad} \frac{1}{r^2} \wedge (\vec{c} \wedge \vec{r})$$

$$= \frac{1}{r^2} \text{rot} (\vec{c} \times \vec{r}) \vec{r} - \frac{1}{r^2} \text{rot } r^2 \vec{c} - \frac{2}{r^4} [(\vec{c} \times \vec{r}) \vec{r} - r^2 \vec{c}] =$$

$$\cancel{\frac{1}{r^2} \text{rot} (\vec{c} \times \vec{r}) \vec{r}} + \text{grad} (\vec{c} \times \vec{r}) \wedge \vec{r} -$$

$$- \frac{1}{r^2} [r^2 \text{rot } \vec{c} + \text{grad } r^2 \wedge \vec{c}] + \frac{2}{r^2} \vec{r} \wedge \vec{c} =$$

$$= \frac{1}{r^2} \vec{c} \wedge \vec{r} - \frac{1}{r^2} 2\vec{r} \wedge \vec{c} + \frac{2}{r^2} \vec{r} \wedge \vec{c} =$$

$$= \frac{1}{r^2} \vec{c} \wedge \vec{r}$$

aplicando rot. novamente:

$$\text{rot} \frac{1}{r^2} \vec{c} \wedge \vec{r} = \frac{1}{r^2} \text{rot} (\vec{c} \wedge \vec{r}) + \text{grad} \frac{1}{r^2} \wedge (\vec{c} \wedge \vec{r})$$

$$= \frac{2\vec{c}}{r^2} + \frac{2}{r^3} \frac{\vec{r}}{r} \wedge (\vec{c} \wedge \vec{r}) =$$

$$= \frac{2\vec{c}}{r^2} - \frac{2}{r^4} [r^2 \vec{c} + (\vec{r} \times \vec{c}) \vec{r}] =$$

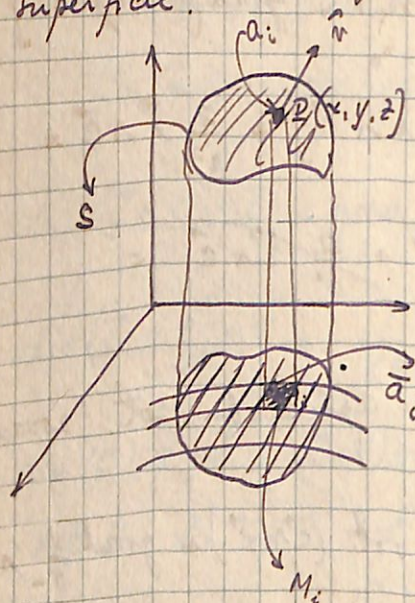
$$\frac{2(\vec{r} \times \vec{c}) \vec{r}}{r^4}$$

$$\Delta_2' (\dots) = \left\{ \frac{2\vec{c}}{r^2} - \frac{6\vec{r} \times \vec{c} \cdot \vec{r}}{r^4} \right\}$$

28. 1. 46

Integrais de superfície

as coord. de $f(x, y, z)$ devem ser coord. de a superfície.



Consideramos um elemento σ_i sobre a superfície.

Temos:

$$\lim_{\sigma_i \rightarrow 0} \sum_{i=1}^n f(x_i, y_i, z_i) \sigma_i \quad (n \rightarrow \infty)$$

$$= I_S = \iint_S f(x, y, z) dS$$

Onde $dS = \sqrt{E G - F^2} du dv$

$$P = 0 + \varphi(u, v)$$

$$E = P'_u \times P'_u$$

$$F = P'_u \times P'_v$$

$$G = P'_v \times P'_v$$

ou $dS = \sqrt{A^2 + B^2 + C^2} du dv$

ou ainda $dS = \frac{dx dy}{\cos \gamma} = \frac{dx dy}{\cos \beta}$

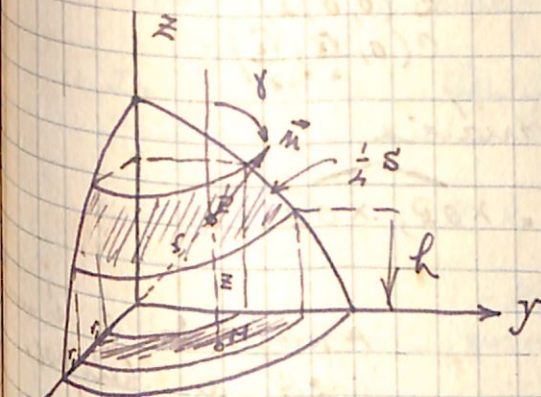
quando $z = \varphi(x, y)$

$$dS = \sqrt{1 + p^2 + q^2} dx dy \quad \begin{cases} p = \frac{\partial z}{\partial x} \\ q = \frac{\partial z}{\partial y} \end{cases}$$

e mais $dS = |P'_u \wedge P'_v| du dv$

Exercícios

Calcular $I = \iint_S z dS$ sendo S a zona de superf. esférica $x^2 + y^2 + z^2 = R^2$ com as bases nos planos $z = h$ e $z = k > h$



Então:

$$I = \iint_S z \frac{dx dy}{\cos \gamma}$$

pela figura observamos que $\cos \gamma = \frac{z}{R}$ donde:

$$I = R \iint_S dx dy =$$

$$= \pi R [r_1^2 - r_2^2] = \pi R [(R^2 - h^2) - (R^2 - k^2)] =$$

$$= \pi R (k^2 - h^2)$$

$$I = \pi R (k^2 - h^2)$$

Pela integral: $\iint_S dx dy$

$$\begin{aligned} x &= \rho \cos \theta \\ y &= \rho \sin \theta \end{aligned} \quad |J| = \rho$$

$$\iint_S \rho d\rho d\theta = \int_0^{2\pi} d\theta \int_{r_2}^{r_1} \rho d\rho = \frac{\rho^2}{2} (r_1^2 - r_2^2) =$$

$$= \pi (k^2 - h^2)$$

Calcular

$$I = \iint_S e \, dS$$

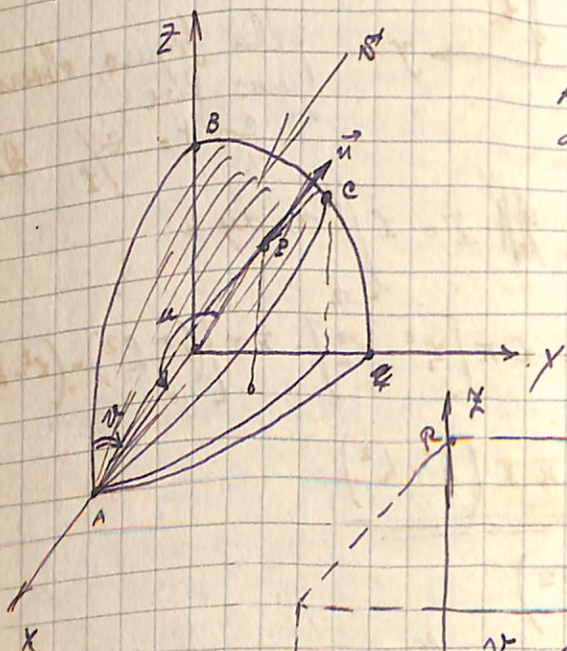
estendido ao triângulo esférico

situado na esfera $x^2 + y^2 + z^2 = 1$

e vértices $A(1, 0, 0)$
 $B(0, 0, 1)$
 $C(0, \frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2})$

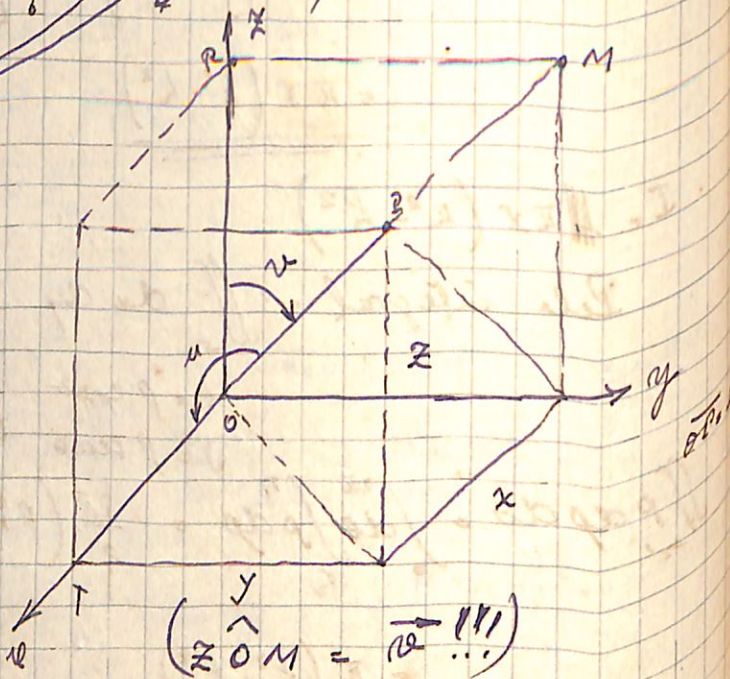
com a mudança de variáveis

$$u = \widehat{OP, Ox} \quad v = \widehat{XOP, XOZ}$$



Aproj. do Δ é um arco de helipse.

Necessitamos de $x = f_1(u, v)$
 $y = f_2(u, v)$
 $z = f_3(u, v)$



$$\widehat{zOM} = \alpha \dots$$

$$|r| = \cos u$$

$$\begin{cases} y = OM \cdot \sin v \\ z = OM \cdot \cos v \end{cases}$$

mas $OM = TP$ donde:

$$OM = \cos u \quad \begin{cases} y = \cos u \cdot \sin v \\ z = \cos u \cdot \cos v \end{cases}$$

Voltemos à integral:

$$I = \iint_S \cos u \cdot \frac{du \, dv \cdot |J|}{\cos \delta}$$

$$\cos \delta = \frac{z}{r} = z = \cos u \cdot \cos v$$

$$|J| = \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} -\sin u & 0 \\ \cos u \sin v & \cos u \cos v \end{vmatrix} = |\sin^2 u \cos v|$$

$$I = \iint_S \cos u \cdot \cos u \cdot du \, dv =$$

$$\int_0^{\pi/2} \int_0^{\pi/4} \cos^2 u \cdot \sin u \, du \, dv = \frac{\pi}{4} \left[\frac{\sin^3 u}{3} \right]_0^{\pi/4} = \frac{\pi}{8}$$

Projetando sobre o plano yOz , obtemos $\frac{1}{8}$ de círculo -

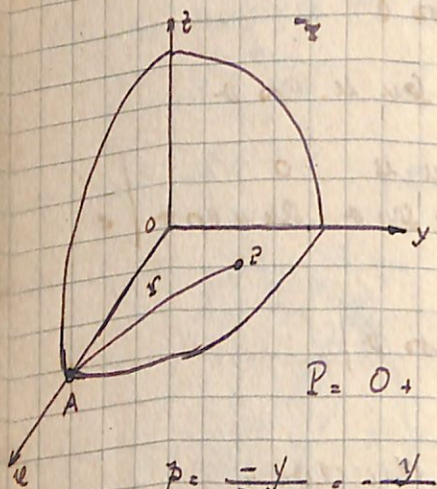
$$I = \iint_S e \frac{dy \, dz}{\cos \alpha} = \iint_S e \frac{dy \, dz}{1} = \iint_S dy \, dz = \frac{\pi}{8}$$

A. 9. 46.

Calcular a integral de superf.:

$I = \iint_S \frac{ds}{r}$ estendida à porção de superfície
 da esfera $x^2 + y^2 + z^2 = 1$
 $u, y, z \geq 0$

onde $r = \overline{AP}$
 $A = (1, 0, 0)$ $P = (u, y, z)$



$r = \sqrt{(u-1)^2 + y^2 + z^2}$
 $ds = \sqrt{1 + p^2 + q^2} \, du \, dy$

$p = \frac{\partial u}{\partial y}$
 $q = \frac{\partial u}{\partial z}$

$P = 0 + \sqrt{1 - (y^2 + z^2)} \, \vec{i} + y \vec{j} + z \vec{k}$

$p = \frac{-y}{\sqrt{1 - (y^2 + z^2)}} = -\frac{y}{u}$ $q = -\frac{z}{u}$

$ds = \sqrt{1 + \frac{y^2}{u^2} + \frac{z^2}{u^2}} \, dy \, dz = \frac{1}{u} \, dy \, dz$

mais ainda:

$r = \sqrt{2 - 2x} = \sqrt{2(1-x)}$ logo:

$I = \iint_S \frac{dy \, dz}{u \sqrt{2(1-u)}} = \frac{1}{\sqrt{2}} \iint_S \frac{dy \, dz}{\sqrt{1-y^2-z^2} \sqrt{1-y^2-z^2}}$

Projetamos sobre o plano (u, z)

$p = \frac{\partial u}{\partial y} = -\frac{y}{u}$ $q = \frac{\partial u}{\partial z} = -\frac{z}{u}$

$ds = \sqrt{1 + p^2 + q^2} \, du \, dy = \sqrt{1 + \frac{y^2}{u^2} + \frac{z^2}{u^2}} \, du \, dy =$

$= \frac{1}{u} \, du \, dy$

$I = \iint \frac{du \, dz}{\sqrt{1-u^2-z^2} \sqrt{2-2u}} = \frac{1}{\sqrt{2}} \int_0^1 \frac{du}{\sqrt{1-u}} \int_0^{\sqrt{1-u^2}} \frac{dz}{\sqrt{1-u^2-z^2}}$

$I_1 = \int_0^1 \frac{1}{\sqrt{1-\left(\frac{z}{\sqrt{1-u^2}}\right)^2}} \frac{dz}{\sqrt{1-u^2}} = \left[\arcsen \frac{z}{\sqrt{1-u^2}} \right]_0^{\sqrt{1-u^2}}$
 $= \frac{\pi}{2}$

$I = \frac{\pi}{2\sqrt{2}} \int_0^1 \frac{du}{\sqrt{1-u}} = \frac{\pi}{2\sqrt{2}} \int_0^1 (1-u)^{-1/2} (-du) =$

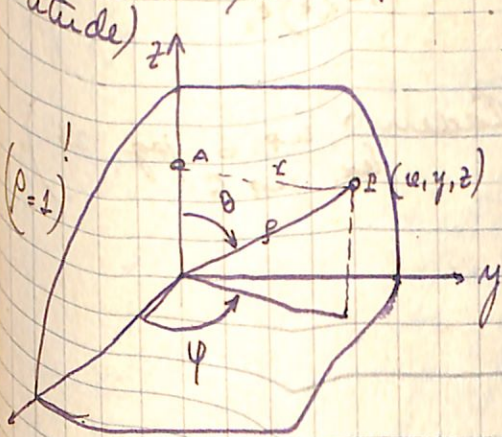
$= -\frac{\pi}{\sqrt{2}} \left[(1-u)^{1/2} \right]_0^1 = \frac{\pi}{\sqrt{2}} = \boxed{\frac{\pi\sqrt{2}}{2}}$ *Independente de r.*

Calcular:

$I = \iint_S \frac{d\sigma}{r^4}$

$r = \overline{AP}$ $A = (0, 0, h)$
 $P = (u, y, z)$ $h > 1$

usando como parâmetros φ (longit.) e θ (colatit.)



$P = 0 + u \vec{i} + y \vec{j} + z \vec{k}$

$u = \text{sen} \theta \cos \varphi$
 $y = \text{sen} \theta \text{sen} \varphi$
 $z = \text{cos} \theta$

$P = 0 + \text{sen} \theta \cos \varphi \vec{i} + \text{sen} \theta \text{sen} \varphi \vec{j} + \text{cos} \theta \vec{k}$

Usamos

$d\sigma = \sqrt{EG-F^2} \, d\theta \, d\varphi$

$\begin{cases} P'_\theta = \text{cos} \theta \cos \varphi \vec{i} + \text{cos} \theta \text{sen} \varphi \vec{j} - \text{sen} \theta \vec{k} \\ P'_\varphi = -\text{sen} \theta \text{sen} \varphi \vec{i} + \text{sen} \theta \cos \varphi \vec{j} \end{cases}$
 $E = P'_\theta \cdot P'_\theta = 1$ $G = P'_\varphi \cdot P'_\varphi = \text{sen}^2 \theta$
 $F = P'_\theta \cdot P'_\varphi = 0$
 donde:

$$dS = \sqrt{z_x^2 + z_y^2} \, dx \, dy = \text{coss} \, dx \, dy$$

Determinemos z : pode-se fazer por G.A.M.

$$z = \sqrt{x^2 + y^2 + (z-h)^2}; \text{ mas pela fig:}$$

$$z^2 = h^2 + 1 - 2h \cos \theta$$

$$I = \iint_D \frac{\text{coss} \, dx \, dy}{(1+h^2-2h \cos \theta)^2}$$

$$= \int_0^{2\pi} d\theta \int_0^{\pi} \frac{\text{coss} \, d\theta}{(1+h^2-2h \cos \theta)^2} \quad \leftarrow \text{estudar esta variac\~{a}o!}$$

$$I_1 = \int_0^{\pi} \frac{\text{coss} \, d\theta}{(1+h^2-2h \cos \theta)^2} = \frac{1}{2h} \int_0^{\pi} (1+h^2-2h \cos \theta)^{-2} d(2h \cos \theta)$$

$$= -\frac{1}{2h} \left[\frac{1}{1+h^2-2h \cos \theta} \right]_0^{\pi} = \frac{2}{(1-h^2)^2}$$

$$I = \frac{4\pi}{(1-h^2)^2} \quad \left(\text{Cadauno no 6 pg 23.} \right)$$

ex. no 6

20.8.46.

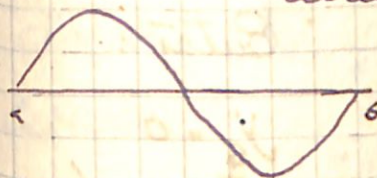
Dr. Proves.

Cálculo de áreas e volumes pf inte-
grais.

1) Áreas.

Uma área pode ser calculada por
integral simples ou dupla.

$\int_a^b y \, dx$ - área relativa, isto é, a par-
te situada acima do eixo dos x
é posit. e a parte situada
abaixo, negativa.



ex: $\int_0^{\pi} \cos x \, dx = 0$

Para se obter a área em val. absoluto
deve-se substituir a expressão anterior por
 $\int_a^b |y| \, dx$

Também se pode calcular área por
integral dupla:

$$\iint_D dx \, dy$$

neste caso a área é sempre
absoluta, desde que se considere
se a variac\~{a}o de x e de
 y sempre no sentido cro-
cente.

2) Volumes

Exalem observac\~{o}es análogas.
Assim: $\int \int z \, dx \, dy$ conduz sempre a um
volume relativo, isto é, para z posit.
posit. e para z neg. é neg.
O vol. absoluto é dado por $\int \int |z| \, dx \, dy$

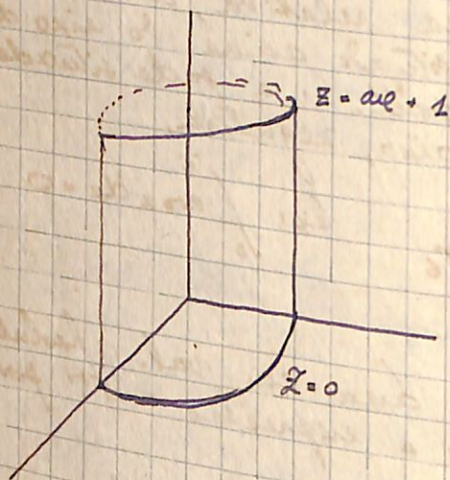
$\iiint dx dy dz$ também fornece volume,
 será absoluto se considerarmos $x, y,$
 z sempre em sentido crescente.

Calcular o baricentro do volume limitado
 pelo cilindro

$$x^2 + y^2 = 1 \text{ e } \text{por planos}$$

$$z = 0$$

$$z = a\sqrt{x^2 + y^2} + 1$$



Então:

$$y_G = 0$$

$$x_G = \frac{1}{V} \int x dV$$

$$z_G = \frac{1}{V} \int z dV$$

Mas no caso: $V = \pi r^2 h = \pi$.

donde $x_G = \frac{1}{V} \int x dV = \pi^{-1} \int x dV$

Calculamos

$$I_1 = \iiint x dx dy dz = \int x dV \rightarrow \text{por mudança}$$

para coordenadas cilíndricas:

$$x = u \cos v$$

$$y = u \sin v$$

$$z = z$$

$$|J| = u$$

$$I_1 = \iiint u^2 \cos v du dv dz =$$

$$= \int_0^1 u^2 du \int_0^{2\pi} \cos v dv \int_0^{a \cos v + 1} dz =$$

$$= \int_0^1 u^2 du \int_0^{2\pi} (a \cos^2 v + \cos v) dv =$$

$$= \int_0^1 u^2 du \int_0^{2\pi} \left[a u \left(\frac{1}{2} + \frac{1}{2} \cos 2v \right) \right] dv =$$

$$= a \pi \int_0^1 u^3 du = a \pi \left[\frac{u^4}{4} \right]_0^1 = \frac{a \pi}{4}$$

donde: $x_G = \frac{1}{4} a$

Calculamos $\int z dV = \iiint z dx dy dz =$

$$= \iiint z u du dv dz = \int_0^1 u du \int_0^{2\pi} dv \int_0^{a \cos v + 1} z dz =$$

$$= \frac{1}{2} \int_0^1 u du \int_0^{2\pi} (a \cos v + 1)^2 dv =$$

$$= \frac{1}{2} \int_0^1 u du \int_0^{2\pi} [a^2 \cos^2 v + 2a \cos v + 1] dv =$$

$$= \frac{2\pi}{2} \int_0^1 (a^2 u^2 + 1) u du = \pi \left[\frac{1}{3} a^2 u^3 + \frac{1}{2} u^2 \right]_0^1 =$$

$$= \frac{\pi}{3} a^2 + \frac{\pi}{2}$$

portanto:

$$z_G = \frac{a^2}{3} + \frac{1}{2}$$

27.8.76

superf. do $z = x^2 + y^2$
 Baricentro do parabolóide int. dos cilindros
 $4x^2 + 16y^2 = 1$ $x, y, z \geq 0$

$$ds = \sqrt{1 + 4x^2 + 16y^2} \, dx \, dy$$

$$\begin{aligned} x &= u \cos v & z &= \frac{1}{8} u \\ y &= u \sin v \end{aligned}$$

$$ds = \frac{1}{8} \sqrt{1 + u^2} \, u \, du \, dv$$

$$S = \frac{1}{8} \int_0^{\pi/2} dv \int_0^1 \sqrt{1 + u^2} \, u \, du = \frac{\pi}{48} (2^{3/2} - 1)$$

$$\text{Daqui: } x_G = \frac{\int x \, ds}{S}$$

$$y_G = \frac{\int y \, ds}{S}$$

$$z_G = \frac{\int z \, ds}{S}$$

$$\int x \, ds = \frac{1}{16} \int_0^{\pi/2} \cos v \, dv \int_0^1 u^2 \sqrt{1 + u^2} \, du$$

Integramos por funções hiperbólicas: -

notemos que:

$$\operatorname{senh} u = \frac{e^u - e^{-u}}{2}$$

$$\operatorname{cosh} u = \frac{e^u + e^{-u}}{2}$$

$$\frac{d \operatorname{senh} u}{du} = \operatorname{cosh} u$$

$$\frac{d \operatorname{cosh} u}{du} = \operatorname{senh} u$$

Todas formas da
 das formas da trigon.

Trigon. hip.
 cíclicas,

obtemos

u cos v por x.h.u e sen v por y.h.u.

No caso seria:

$$\begin{cases} u = \operatorname{sh} u & - 1 + u^2 = \operatorname{ch} u \\ du = \operatorname{ch} u \, du \end{cases}$$

$$u = 0 \rightarrow \operatorname{senh} u = 0 \text{ para } u = 0$$

$$u = 1 \rightarrow \frac{e^x - e^{-x}}{2} = 1 \quad \left\{ \begin{aligned} e^x - \frac{1}{e^x} &= 2 \\ e^{2x} - 1 &= 2e^x \text{ ou } (e^x)^2 - 2e^x - 1 = 0 \end{aligned} \right.$$

$$e^{2x} - 1 = 2e^x \text{ ou } (e^x)^2 - 2e^x - 1 = 0$$

$$\text{donde: } e^x = 1 \pm \sqrt{2} \text{ ou}$$

$$u = \ln(1 + \sqrt{2})$$

$$\text{lago: } I = \int_0^{\ln(1+\sqrt{2})} \operatorname{sh}^2 u \cdot \operatorname{ch}^2 u \, du = \frac{1}{4} \int_0^{\ln(1+\sqrt{2})} \operatorname{sh}^2 u \cdot \operatorname{ch}^2 u \, du$$

$$= \frac{1}{4} \int_0^{\ln(1+\sqrt{2})} \operatorname{sh}^2 2x \, dx$$

Observemos que, de:

$$\operatorname{sen}^2 x = \frac{1}{2} - \frac{1}{2} \cos 2x$$

obtemos $-\operatorname{sh}^2 u = \frac{1}{2} - \frac{1}{2} \operatorname{ch} 2x$
 fica

$$\begin{aligned} I_1 &= \frac{1}{4} \int_0^{\ln(1+\sqrt{2})} \left(-\frac{1}{2} + \frac{1}{2} \operatorname{ch} 4u \right) du = \\ &= \frac{1}{4} \left[-\frac{u}{2} + \frac{1}{8} \operatorname{sh} 4u \right]_0^{\ln(1+\sqrt{2})} = \frac{1}{8} \left[\frac{1}{4} \operatorname{sh} 4 \ln(1+\sqrt{2}) - \ln(1+\sqrt{2}) \right] \end{aligned}$$

volvendo atrás:

$$x_G = \frac{1}{128 \cdot S} \left[\frac{1}{4} \operatorname{sh} 4 \ln(1+\sqrt{2}) - \ln(1+\sqrt{2}) \right]$$

$$y_G = \frac{1}{S} \int y ds$$

$$\int y ds = \frac{1}{32} \int_0^{\pi/2} \sin v \cdot dr \int u^2 \sqrt{1+u^2} du$$

$$y_G = \frac{1}{256 S} [\dots]$$

$$z_G = \frac{1}{S} \int z ds \quad z = u^2 + 2y^2$$

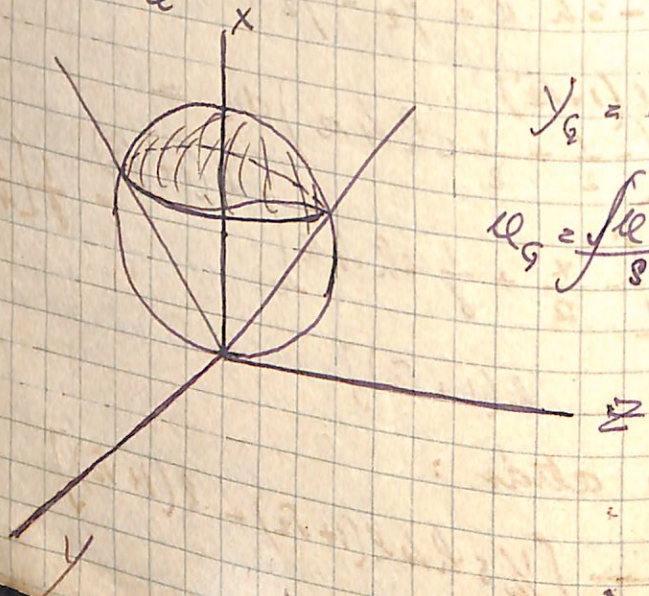
$$z = \frac{1}{4} u^2 \left[\cos^2 v + \frac{1}{2} \sin^2 v \right] = \frac{1}{4} u^2 \left[1 - \frac{1}{2} \sin^2 v \right]$$

$$\int z ds = \frac{1}{32} \int_0^{\pi/2} \left(1 - \frac{1}{2} \sin^2 v \right) dr \int u^3 \sqrt{1+u^2} du$$

fazer $1+u^2 = t^2$

$$z_G = \frac{\pi}{640} (\sqrt{2} + 1)$$

Determ. o baric. de superf. esferica
 $x^2 + y^2 + z^2 = 2a$, interna ao cone
 $y^2 + 7z^2 = u^2$



$$y_G = z_G = 0$$

$$x_G = \frac{1}{S} \int x ds$$

empregue-se coordenadas polares no espaco.

no caso: $u = \rho \cos \theta$

$$y = \rho \sin \theta \cos \varphi$$

$$z = \rho \sin \theta \sin \varphi$$

$$u^2 + y^2 + z^2 = \rho^2 = 2 \rho \cos \theta \text{ logo,}$$

$$\rho = 2 \cos \theta$$

$$P = 0 + 2 \cos^2 \theta \vec{i} + 2 \sin \theta \cos \theta \cos \varphi \vec{j} + 2 \sin \theta \cos \theta \sin \varphi \vec{k}$$

Esta e' a repres. param. de superf. de esfera em fun. dos parametros θ e φ

$$ds = \sqrt{P'_\theta \wedge P'_\varphi} \, d\theta \, d\varphi = 2 \sin 2\theta \, d\theta \, d\varphi$$

$$\varphi \rightarrow 0 \text{ a } 2\pi$$

$$\theta \rightarrow 0 \text{ a } \frac{\pi}{2} \text{ (ef. de simetria int. das 2 superf.)}$$

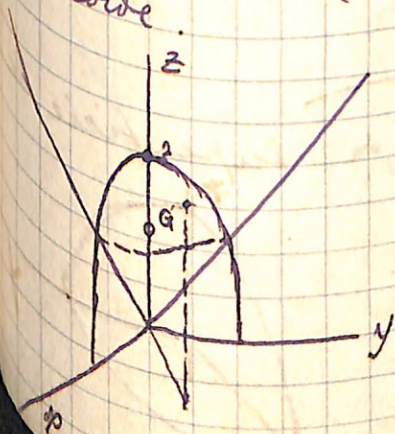
8.9.946.

Consid. o cone $a^2 x^2 + y^2 = z^2$ e o para-boloide $a^2 x^2 + y^2 = 2-z$ determinar o baric. de volume limitada pelo cone e pelo paraboloide. ($z \geq 0$)
 O cone e' eliptico.

Neste caso:
 $x_G = y_G = 0$ e

$$z_G = \frac{1}{V} \int z \, dV$$

$V = \iiint dV$ mudancas para



Coordenadas polares cilíndricas (polares)

$$x = \rho \cos \theta \quad y = \rho \sin \theta \quad z = z$$

$$|\vec{r}| = \rho/a$$

$$V = \iiint \rho/a \, d\rho \, d\theta \, dz$$

Ficamos com:

$$\left\{ \begin{array}{l} \text{con: } \rho^2 = z^2 \\ \text{parabl: } \rho^2 = 2 - z \end{array} \right.$$

$$V = \int_0^1 \int_0^{2\pi} \int_{\rho}^{2-\rho^2} \rho/a \, dz \, d\theta \, d\rho = \int_0^1 \int_0^{2\pi} \rho/a (2 - \rho^2 - \rho) \, d\theta \, d\rho$$

$$= \frac{2\pi}{a} \int_0^1 (2\rho - \rho^3 - \rho^2) \, d\rho = \frac{2\pi}{a} \left[\frac{2\rho^2}{2} - \frac{\rho^4}{4} - \frac{\rho^3}{3} \right]_0^1$$

$$= \frac{5\pi}{6a} \quad \text{Volume } = \int_0^1 z \, dz = \dots$$

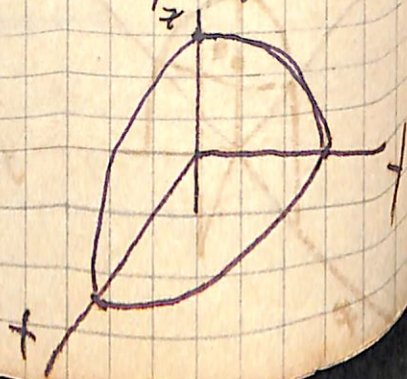
$$= \frac{6a}{5\pi} \int_0^1 \int_0^{2\pi} \int_{\rho}^{2-\rho^2} z \, dz \, d\theta \, d\rho = \frac{6a}{5\pi} \int_0^1 \int_0^{2\pi} \left[\frac{z^2}{2} \right]_{\rho}^{2-\rho^2} \, d\theta \, d\rho$$

$$= \frac{12\pi a}{2,5\pi} \int_0^1 \rho (4 + \rho^4 - 5\rho^2) \, d\rho = \frac{12a}{10} \left[2\rho^2 + \frac{\rho^5}{5} - \frac{5\rho^3}{3} \right]_0^1$$

$$= \frac{12a}{10} \cdot \frac{11}{12} = \frac{11}{10} a$$

achar o baricentro da superfície da
um octante de esfera.

$$x^2 + y^2 + z^2 = a^2$$



Devido à equação de esfera ter simetria em relação aos três eixos, dev. nos ter:

$$X_G = Y_G = Z_G \quad \text{então, p. ex.}$$

$$X_G = \frac{1}{S} \int u \, ds \quad S = \pi a^2/2$$

$$I_1 = \int_{\Omega} u \, ds = \int u \sqrt{EG - F^2} \, d\theta \, d\rho$$

$$\text{fazendo } \begin{cases} u = \rho \cos \theta \cdot \cos \varphi \\ y = \rho \sin \theta \cdot \sin \varphi \\ z = \rho \cos \theta \end{cases} \quad \rho = a$$

$$\vec{r} = 0 + a \cos \theta \cos \varphi \vec{i} + a \sin \theta \sin \varphi \vec{j} + a \cos \theta \vec{k}$$

$$\vec{r}'_{\theta} = -a \sin \theta \cos \varphi \vec{i} + a \cos \theta \sin \varphi \vec{j} - a \sin \theta \vec{k}$$

$$\vec{r}'_{\varphi} = -a \sin \theta \sin \varphi \vec{i} + a \cos \theta \cos \varphi \vec{j}$$

$$I_1 = \int_{\Omega} x \sqrt{|\vec{r}'_{\theta} \wedge \vec{r}'_{\varphi}|} \, d\theta \, d\rho$$

$$|\vec{r}'_{\theta} \wedge \vec{r}'_{\varphi}| = a^2 \sin \theta \sqrt{\sin^2 \theta \cos^2 \varphi + \sin^2 \theta \sin^2 \varphi + \cos^2 \theta} = a^2 \sin \theta$$

$$I_1 = a^3 \int_0^{\pi/2} \int_0^{\pi/2} \sin^2 \theta \cos \varphi \, d\theta \, d\varphi = a^3 \int_0^{\pi/2} \sin^2 \theta \, d\theta \int_0^{\pi/2} \cos \varphi \, d\varphi =$$

$$= \frac{a^3}{2} \cdot \frac{\pi}{2} = \frac{a^3 \pi}{4}$$

$$X_G = \frac{a^3 \pi}{4} / \frac{\pi a^2}{2} = \frac{2a^3 \pi}{4\pi a^2} = \frac{a}{2}$$

9.9.46

Entre na provinha.

Sejam três funções $P(u, y, z)$, $Q(u, y, z)$, $R(u, y, z)$ contínuas e P a prim. derivada 2.ª ordem, contínuas.

e seja a superf. $\begin{cases} x = \varphi_1(u, v) \\ y = \varphi_2(u, v) \\ z = \varphi_3(u, v) \end{cases}$

Por definições:

$$\iint_S (P \cos \alpha + Q \cos \beta + R \cos \gamma) dS \quad \text{é uma inte.} \\ \text{geral de superfície.}$$

Outra notação:

$$\iint_S P dy dz + Q dz du + R du dy = (\text{7. def.}) \\ = \iint_D P_1 \frac{d(y, z)}{d(u, v)} + Q_1 \frac{d(z, u)}{d(u, v)} + R_1 \frac{d(u, y)}{d(u, v)}$$

$$\begin{vmatrix} \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \end{vmatrix} \quad (\text{1.ª val. abs.})$$

$$P_1 = P[\varphi_1(u, v), \varphi_2, \varphi_3] \\ Q_1 = Q[\varphi_1, \varphi_2, \varphi_3]$$

estendida ao domínio de variações de u e v .

Lin. - não se toma $\cos \alpha, \cos \beta, \cos \gamma$ em absoluto. Deve-se sempre convencionar qual das normais se usa.

Calcular:

$$I = \iint_S x dy dz + y dz du + z du dy \quad (\text{Potter pg 107})$$

sendo $S: \begin{cases} x = (a + b \cos u) \cos v \\ y = (a + b \cos u) \sin v \\ z = b \sin u \end{cases}$

$a \geq b$ u, v naturais, $0 \leq u, v \leq 2\pi$

$$I = \iint_D P_1 \frac{d(y, z)}{d(u, v)} + Q_1 + \dots$$

$$\textcircled{1} \frac{d(y, z)}{d(u, v)} = \begin{vmatrix} -b \sin u \sin v & (a + b \cos u) \cos v \\ b \cos u & 0 \end{vmatrix} =$$

$$= - (a + b \cos u) b \cos u \cos v$$

$$\textcircled{2} \frac{d(z, u)}{d(u, v)} = \begin{vmatrix} b \cos u & 0 \\ -b \sin u \cos v & -(a + b \cos u) \sin v \end{vmatrix} =$$

$$= - (a + b \cos u) b \cos u \sin v$$

$$\textcircled{3} \frac{d(u, y)}{d(u, v)} = \begin{vmatrix} -b(a + b \cos u) \sin u \cos^2 v & - \\ -b(a + b \cos u) \sin u \sin^2 v & \end{vmatrix} =$$

$$I = \iint_D [-b(a + b \cos u)^2 \cos u \cos^2 v - b(a + b \cos u)^2 \cos u \sin^2 v - b^2(a + b \cos u) \sin^2 u] du dv$$

$$= -b \iint_D (a + b \cos u) [(a + b \cos u) \cos^2 v + b \sin^2 v] du dv$$

$$= -b \iint_D (a \cos u + b \cos^3 u) (a \cos u + b) du dv$$

$$= -b \iint_D [(a^2 + b^2) \cos u + ab \cos^2 u + ab] du dv$$

$$= -b \int_0^{2\pi} dv \int_0^{2\pi} [(a^2 + b^2) \cos u + ab(\cos^2 u + 1)] du$$

$$= -2\pi ab^2 \int (\cos^2 u + 1) du = -2\pi ab^2 \int \left(\frac{3}{2} + \frac{1}{2} \cos 2u\right) du =$$

$$= -\frac{6ab^2\pi^2}{2}$$

Calcular: $I = \iint_S \frac{k(x \cos \alpha + y \cos \beta) + T \cos \gamma}{r^2 + y^2} dS$

Seja $k = \frac{y^2}{x}$ $T = \frac{2\sqrt{1-y^2}}{x} = 2x + \frac{y}{x}$

Seja S a porção da superf. $x^2 + y^2 = 4z^2$ (cone duplo na origem)

$$x > 0 \quad y > 0$$

$$\frac{1}{4} \leq z \leq \frac{1}{2}$$

pode-se fazer $x = u$ e $y = v$, ou outras.

10.9.46.

Chama-se momento de inércia de 1 sist^a de pontos materiais $P_i (m_i)$ em rel. a um eixo i a expressão

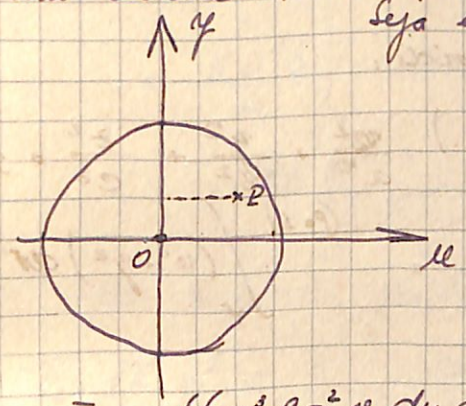
$$I = \sum m_i d_i^2$$

sendo d_i as dist. de P_i ao eixo.

No caso de distribuições cont. de massa, a somatória deve ser substituída por \int .

Exercícios:

Momento de inércia de um círculo em relação a um diâmetro. Seja em rel. a Oy :



$$I_{Oy} = \int_S x^2 ds$$

$$x^2 + y^2 = R^2 \text{ (círculo)}$$

Substituímos:

$$\begin{cases} x = u \cos v & |J| = u \\ y = u \operatorname{sen} v \end{cases}$$

$$I_{Oy} = \iint u^3 \cos^2 v \, du \, dv = \int_0^{2\pi} \cos^2 v \, dv \int_0^R u^3 \, du =$$

$$= \frac{R^4}{4} \int_0^{2\pi} \cos^2 v \, dv = \frac{R^4}{4} \int_0^{2\pi} \left(\frac{1}{2} + \frac{1}{2} \cos 2v\right) dv =$$

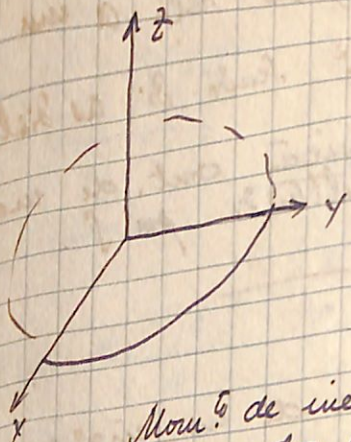
$$= \frac{R^4}{4} \int_0^{2\pi} \frac{1}{2} dv + \frac{R^4}{4 \cdot 2} \left[\frac{v}{2} + \frac{\operatorname{sen} 2v}{2} \right]_0^{2\pi} =$$

$$= \frac{R^4 \cdot 2\pi}{8} = \frac{\pi R^4}{4}$$

mas $ds = du$
Logo:

$$I = \frac{mR^2}{4} = \pi R^2 \frac{R^2}{4}$$

Cálculo do momento de inércia do mesmo círculo em rel. a um eixo vertical.



$$I_{Oz} = \int (x^2 + y^2) ds =$$

$$= 2I_{Oy} = \frac{mR^2}{2}$$

Mom. de inércia de um elipsoide em relação a um dos eixos.

Equações do elipsoide:

$$\frac{z^2}{c^2} + \frac{y^2}{b^2} = 1 \text{ (elipse)} \quad \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

$$I = \int_V l^2 dm = \int_V (x^2 + y^2) dV$$

$$\frac{dx}{dt} = 1$$

$$I = \iiint_E (x^2 + y^2) dx dy dz$$

$$\begin{cases} x = au \cos v \\ y = bu \sin v \\ z = z \end{cases} \quad |J| = a \cdot b \cdot u$$

$$I = \int dz \int_0^{2\pi} \int_0^1 a^3 b u^3 \cos^2 v du dv + I_2$$

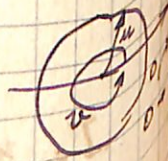
$$u^2 + \frac{z^2}{c^2} = 1 \quad u = \sqrt{1 - \frac{z^2}{c^2}}$$

$$I_1 = a^3 b \int_{-c}^c dz \int_0^{2\pi} \cos^2 v dv \int_{-\sqrt{1-\frac{z^2}{c^2}}}^{\sqrt{1-\frac{z^2}{c^2}}} u^3 du =$$

(0, u)

ou (0, -u)

engano no sinal



$$= \frac{\pi a^3 b}{4} \int_{-c}^{+c} dz \cdot 2 \left(1 - \frac{z^2}{c^2}\right)^2$$

$$= \frac{\pi a^3 b}{2} \int_{-c}^{+c} \left(1 - \frac{z^2}{c^2}\right)^2 dz =$$

$$= \frac{\pi a^3 b}{2} \left[z + \frac{z^5}{5c^4} - \frac{2}{3} \frac{z^3}{3c^2} \right]_{-c}^c$$

$$= \frac{\pi a^3 b}{2} \left(2c + \frac{2c^5}{5c^4} - \frac{4c^3}{3c^2} \right) =$$

$$= \frac{\pi a^3 b}{2} \left(\frac{30c + 6c - 20c}{15} \right) =$$

$$= \frac{16 \pi a^3 b c}{2 \cdot 15} = \frac{8 \pi a^3 b c}{15}$$

de maneira análoga calcularíamos

$$I_2 = \frac{8 \pi}{15} b^3 a c \quad \text{finalmente:}$$

$$I = I_1 + I_2 = \frac{8 \pi abc}{15} [a^2 + b^2]$$

mas $V_{\text{elipsoide}} = \frac{4}{3} \pi abc$ logo:

$$I = \frac{2}{5} m (a^2 + b^2)$$

($I_2 = \frac{1}{5} m (a^2 + b^2)$)
de correção de
sinal?

Caso de esfera.

$$x^2 + y^2 + z^2 = R^2$$

$$I = \int l^2 dm = \iiint (x^2 + y^2) dx dy dz$$

$$\left. \begin{aligned} u &= u \sin \theta \cdot \cos \varphi \\ y &= u \sin \theta \cdot \sin \varphi \\ z &= u \cos \theta \end{aligned} \right\} |J| = u^2 \sin \theta$$

$$I = \iiint u^4 \sin^3 \theta \, du \, d\theta \, d\varphi$$

$$= \int_0^a u^4 \, du \cdot \int_0^\pi \sin^3 \theta \, d\theta \cdot \int_0^{2\pi} d\varphi = I_0$$

$$= \frac{1}{5} a^5 \cdot \frac{4}{3} \cdot 2\pi = \frac{2a^2}{5} \left(\frac{4\pi a^3}{3} \right) = \frac{2}{5} \pi a^5$$

$$I_0 = \int_0^\pi \sin \theta (1 + \cos^2 \theta) \, d\theta = \left(-\cos \theta + \frac{1}{3} \sin^3 \theta \right) \Big|_0^\pi = \frac{4}{3}$$

Recapitulação.

9.10.946

Calcular $\text{div } \vec{u}$, sendo

$$\vec{u} = \lambda \vec{a} + r^2 \sin \theta \cdot \vec{b} + r \sin \theta \cos \theta \vec{c},$$

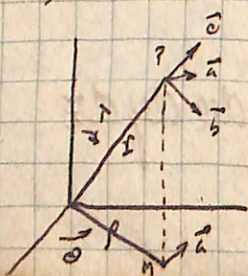
e $P(r, \theta, \lambda)$ e mais $\vec{a}, \vec{b}, \vec{c}$, os vetores normais às sup. $\theta = c^e$, $\lambda = d^e$ e $r = e^e$.

Então:

$$\begin{aligned} \text{div } \vec{u} &= \lambda \text{div } \vec{a} + \text{grad } \lambda \times \vec{a} + \\ &+ r^2 \sin \theta \text{div } \vec{b} + \text{grad } r^2 \sin \theta \times \vec{b} + \\ &+ r \sin \theta \cos \theta \text{div } \vec{c} + \text{grad } r \sin \theta \cos \theta \times \vec{c} \end{aligned}$$

Valem as rel.:

$$\begin{aligned} \vec{a} &= \vec{c} \wedge \vec{b} \\ \vec{b} &= \vec{a} \wedge \vec{c} \\ \vec{c} &= \vec{b} \wedge \vec{a} \end{aligned} \quad \text{pois}$$



$\vec{a}, \vec{b}, \vec{c}$ formam um triêdro triortogonal
Calc. os gradientes.

$$1) \text{grad } \lambda = \lim_{h \rightarrow 0} \left(\frac{\Delta \lambda}{\Delta h} \right) \vec{b} = \frac{\vec{b}}{r}$$

$$2) \text{grad } r^2 \sin \theta = r^2 \text{grad } \sin \theta + \sin \theta \text{grad } r^2 =$$

$$= r^2 \cos \theta \text{grad } \theta + 2r \sin \theta \text{grad } r$$

$$\text{grad } \theta = \frac{\vec{a}}{r} \cdot \frac{\vec{a}}{r \sin \theta}$$

$$\text{grad } r = \vec{c}$$

$$\text{grad } r^2 \sin \theta = \boxed{r^2 \cos \theta \cdot \frac{\vec{a}}{r \sin \theta} + \frac{2r \sin \theta}{r} \vec{c}}$$

$$3) \text{grad } \sin \theta \cos \theta =$$

$$= \sin \theta \text{grad } \cos \theta + \cos \theta \text{grad } \sin \theta =$$

$$= -\sin \theta \sin \theta \text{grad } \theta + \cos \theta \cos \theta \text{grad } \theta =$$

$$= -\frac{\sin \theta \cos \theta}{r \sin \theta} \vec{a} + \frac{\cos \theta \sin \theta}{r} \vec{b} =$$

$$= -\frac{\sin \theta}{r} \vec{a} + \frac{\cos \theta \cos \theta}{r} \vec{b}$$

Calc. os div.

$$\text{div} (\vec{v}_1 \wedge \vec{v}_2) = \vec{v}_2 \times \text{rot } \vec{v}_1 - \vec{v}_1 \times \text{rot } \vec{v}_2$$

$$\text{donde: } \text{div } \vec{a} = \text{div} (\vec{c} \wedge \vec{b}) =$$

$$\vec{b} \times \text{rot } \vec{c} - \vec{c} \times \text{rot } \vec{b}$$

$$\text{rot } \vec{c} = \text{rot grad } r = 0$$

$$\vec{b} = r \text{grad } \lambda \quad \text{rot } \vec{b} = \text{rot } r \cdot \text{grad } \lambda =$$

$$= r \text{rot grad } \lambda + \text{grad } r \wedge \text{grad } \lambda = 0$$

$$= \vec{c} \wedge \frac{\vec{b}}{r} = \frac{\vec{a}}{r} \dots$$

$$\operatorname{div} \vec{a} = \vec{c} \times \frac{\vec{a}}{r} = 0$$

Por outro caminho (definições):

$$\operatorname{rot} \vec{b} = \operatorname{grad} \alpha \vec{b} = \operatorname{grad} \frac{d(r \operatorname{grad} \lambda)}{dr}$$

$$\frac{df \vec{u}}{ds} = f \frac{d\vec{u}}{ds} + H(\operatorname{grad} f, \vec{u}) \vec{s}$$

$$\frac{d(r \operatorname{grad} \lambda)}{dr} \vec{s} = r \frac{d \operatorname{grad} \lambda}{dr} \vec{s} + H(\operatorname{grad} \lambda, \vec{s}) \vec{s}$$

$$= r \frac{d \frac{\vec{b}}{r}}{dr} \vec{s} + H\left(\vec{c}, \frac{\vec{b}}{r}\right) \vec{s} \dots$$

$$\operatorname{rot} [(\vec{c} \wedge \vec{r}) \wedge \vec{r}] = \operatorname{grad} d[(\vec{c} \wedge \vec{r}) \wedge \vec{r}] =$$

$$= \operatorname{grad} \left[(\vec{c} \wedge \vec{r}) \wedge \frac{d\vec{r}}{dr} + \frac{d(\vec{c} \wedge \vec{r})}{dr} \wedge \vec{r} \right] =$$

$$\left(\text{sabendo } f \cdot \frac{d\vec{r}}{dr} \vec{s} = \vec{s} \right)$$

$$= 2(\vec{c} \wedge \vec{r}) + \operatorname{grad} \left(\frac{d\vec{c} \wedge \vec{r}}{dr} \wedge \vec{r} \right) =$$

$$= 2(\vec{c} \wedge \vec{r}) + \operatorname{grad} \left[(\vec{c} \wedge \frac{d\vec{r}}{dr}) \wedge \vec{r} \right] =$$

$$= 2(\vec{c} \wedge \vec{r}) + \operatorname{grad} \left[(\vec{c} \times \vec{r}) \frac{d\vec{r}}{dr} - \left(\frac{d\vec{r}}{dr} \times \vec{r} \right) \vec{c} \right]$$

$$H(\vec{a}, \vec{b}) \vec{v} = \underbrace{(\vec{a} \times \vec{b})}_{\text{não existe vetor}} \vec{v} \quad \text{port.}$$

$$\operatorname{rot} [(\vec{c} \wedge \vec{r}) \wedge \vec{r}] = 2(\vec{c} \wedge \vec{r}) + 2H(\vec{r}, \vec{c}) =$$

$$= 2(\vec{c} \wedge \vec{r}) + (\vec{c} \wedge \vec{r}) = 3(\vec{c} \wedge \vec{r})$$

$$\text{pois } \forall H(\vec{a}, \vec{b}) = \frac{1}{2} \vec{a} \wedge \vec{b}$$

14.10.946.

Questões na prova.

$$\Delta_2 e^{\rho^2} \vec{c} \wedge \vec{r}$$

$$\vec{c} = \vec{c}^e \quad \rho = |\vec{c} \wedge \vec{r}| \quad r = \rho - 0.$$

$$\Delta_2 \equiv \operatorname{grad} \operatorname{div} - \operatorname{rot} \operatorname{rot}.$$

$$\operatorname{div} e^{\rho^2} \vec{c} \wedge \vec{r} = e^{\rho^2} \operatorname{div} \vec{c} \wedge \vec{r} + \operatorname{grad} e^{\rho^2} \times \vec{c} \wedge \vec{r}$$

$$\operatorname{div} \vec{c} \wedge \vec{r} = \vec{r} \times \operatorname{rot} \vec{c} - \vec{c} \times \operatorname{rot} \vec{r} = 0 - 0$$

$$\operatorname{grad} e^{\rho^2} = 2\rho e^{\rho^2} \operatorname{grad} \rho =$$

$$\operatorname{grad} \rho = \frac{(\vec{c} \wedge \vec{r}) \wedge \vec{c}}{\rho}$$

$$\operatorname{grad} e^{\rho^2} = 2e^{\rho^2} (\vec{c} \wedge \vec{r}) \wedge \vec{c}$$

$$\operatorname{div} e^{\rho^2} \vec{c} \wedge \vec{r} = \operatorname{grad} e^{\rho^2} \times \vec{c} \wedge \vec{r} =$$

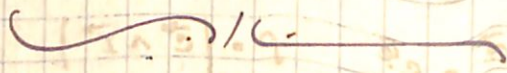
$$= 2e^{\rho^2} (\vec{c} \wedge \vec{r}) \wedge \vec{c} \times (\vec{c} \wedge \vec{r}) = 0$$

$$\operatorname{rot} e^{\rho^2} \vec{c} \wedge \vec{r} = e^{\rho^2} \operatorname{rot} \vec{c} \wedge \vec{r} + \operatorname{grad} e^{\rho^2} \wedge (\vec{c} \wedge \vec{r})$$

$$\operatorname{rot} \vec{c} \wedge \vec{r} = 2\vec{c}$$

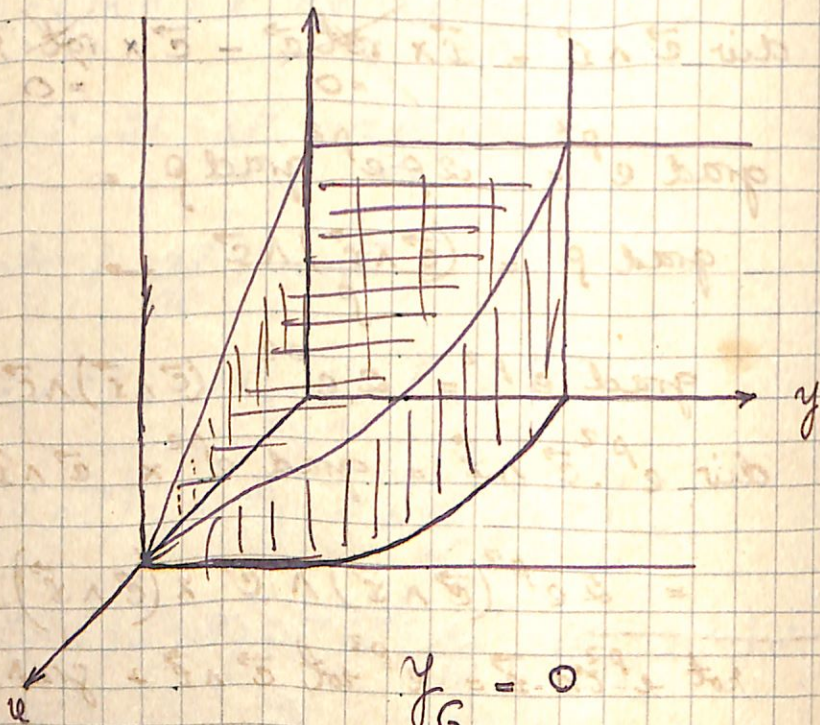
$$\begin{aligned} \text{rot } e^{\rho^2} (\vec{c} \wedge \vec{r}) &= 2e^{\rho^2} \vec{c} + 2e^{\rho^2} (\vec{c} \wedge \vec{r}) \wedge \vec{c} \wedge (\vec{c} \wedge \vec{r}) \\ &= 2e^{\rho^2} \left[\vec{c} + (\vec{c} \wedge \vec{r}) \wedge \vec{c} \wedge (\vec{c} \wedge \vec{r}) \right] \cdot c \\ &= 2e^{\rho^2} \left[\vec{c} + \rho^2 \vec{c} - 0 \right] = \\ &= 2e^{\rho^2} \vec{c} (1 + \rho^2) \end{aligned}$$

$$R.: 4e^{\rho^2} (1 + \rho^2) |\vec{c}|^2 \vec{c} \wedge \vec{r}$$



lim. Calc. o centro de gravidade do vol. pelo cif. $x^2 + y^2 = r^2$ e os planos

$$ax + r^2 = az \quad e \quad z = 0$$

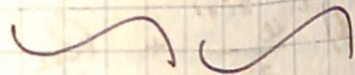


$$y_G = 0$$

$$Q_G = \frac{1}{V} \int \rho \, dV \quad z_G = \frac{1}{V} \int z \, dV$$

$$V = \pi r^2 a$$

$$Q_G = \frac{1}{\pi r^2 a} \int \rho \, dV \, dy \, dz$$



Questões de outra turma:

$$I = \iint z \, dS$$

sendo $S \begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \\ z = \rho e^{\rho^2} \end{cases}$ este jn. e' o campo.

$$\left\{ \begin{array}{l} 0 \leq \theta \leq \pi/2 \\ 0 \leq \rho \leq 1 \end{array} \right.$$

15. 10. 946

Dr. Paves.

Desenv. em serie arctge.

Consideremos a identidade:

$$\frac{1}{1+x^2} = \frac{1 - (-x^2)^n + (-x^2)^n}{1 - (-x^2)^{n+1}} = \frac{1 - (-x^2)^n}{1 - (-x^2)} + \frac{(-x^2)^n}{1 + x^2}$$

$$\text{ou seja, } \frac{1 - y^n}{1 - y} = 1 + y + y^2 + y^3 + \dots + y^{n-1}$$

$$\text{logo } \frac{1}{1+x^2} = 1 + (-x^2) + (-x^2)^2 + \dots + (-x^2)^{n-1} + \frac{(-x^2)^n}{1+x^2}$$

$$+ \frac{(-x^2)^n}{1+x^2}$$

Integrando-se membro a

membro:

$$\int_0^u \frac{du}{1+u^2} = \sum_{i=0}^{n-1} \int_0^u (-u^2)^i du + \int_0^u \frac{(-u^2)^n}{1+u^2} du$$

$$\arctg u = \sum_{i=0}^{n-1} \frac{(-u^2)^{i+1}}{i+1} + R_n$$

$$\arctg u = \sum_{i=0}^{n-1} (-1)^i \frac{u^{2i+1}}{2i+1} + R_n$$

Calculamos $\lim_{n \rightarrow \infty} R_n$

$$R_n = \int_0^u \frac{(-u^2)^n}{1+u^2} du = (-1)^n \int_0^u \frac{1}{1+u^2} \cdot u^{2n} du$$

Aplicando o 2º teorema da média (ver)

$$R_n = (-1)^n \frac{1}{1+\theta u^2} \int_0^u u^{2n} du$$

$0 \leq \theta \leq 1$

$$R_n = (-1)^n \frac{1}{1+\theta u^2} \cdot \frac{u^{2n+1}}{2n+1}$$

Será $\lim_{n \rightarrow \infty} R_n = 0$ para $|u| \leq 1$

Conclusão:

$\arctg u$ é desenvolvível em série de potências no intervalo fechado $-1, +1$ e o desenvolvimento é:

$$\arctg u = \sum_{i=0}^{\infty} (-1)^i \frac{u^{2i+1}}{2i+1} =$$

$$= u - \frac{u^3}{3} + \frac{u^5}{5} - \dots$$

Em particular para $u=1$ resulta

$$\arctg 1 = \pi/4 = 1 - \frac{1}{3} + \frac{1}{5} - \dots$$

Exercício 4 sol.:

Provar $f. \frac{\pi^2}{6} = 1 + \frac{1}{2^2} + \frac{1}{3^2} + \frac{1}{4^2} + \dots + \frac{1}{n^2} + \dots$

Consid. a série

$$f(x) = \frac{x+x^3}{2^2} + \frac{x^3}{3^2} + \frac{x^5}{4^2} + \dots + \frac{x^n}{n^2} + \dots$$

O raio de convergência desta série é:

$$\lim_{n \rightarrow \infty} \frac{\frac{1}{n^2}}{\frac{1}{(n+1)^2}} = \lim_{n \rightarrow \infty} \left(\frac{n+1}{n}\right)^2 = 1$$

portanto a série é convergente no int. aberto $-1, +1$ e uniforme e conv. em ff. int. fechado $-1, +1$ a este.

Raciocinando apenas neste ultº intervalo, pode-se derivar a série termo a termo.

Derivando, obtém-se

$$f'(x) = 1 + \frac{x}{2} + \frac{x^3}{3} + \dots + \frac{x^{n+1}}{n} + \dots$$

portanto se $f'(x) = x + \frac{x^2}{2} + \frac{x^3}{3} + \dots + \frac{x^n}{n} + \dots$

derivando novamente -

$$x f''(x) + f'(x) = 1 + x + x^2 + \dots + x^{n+1} + \dots$$

f. é uma série geométrica e convergente para $|x| < 1$. Chegamos a

$$x f''(x) + f'(x) = \frac{1}{1-x}$$

uma eq. difer., donde

$$x f''(x) + f'(x) = \frac{1}{1-x}$$

part. a $f'(x) = -\ln|x-1|$ ou

$$\frac{f''(x)}{f'(x)} = -\frac{1}{x}$$

determinamos a part. a

$$f'(x) = \frac{c}{x}$$

cf. não homogênea seja verificada - para isto consideremos φ variável.

$$f''(u) = \frac{c'}{u} \text{ donde em } \textcircled{1}$$

$$c' = \frac{1}{1-u} \rightarrow c = -\ln(1-u) + c_1$$

$$\text{port.}^{\circ} f'(u) = \frac{c_1}{u} - \frac{\ln(1-u)}{u}$$

$$\text{notando f. } f'(0) = 1 \quad \textcircled{C}$$

conclui-se que $c_1 = 0$ port.º

$$f''(u) = -\int \frac{\ln(1-u)}{u} du \rightarrow$$

$$f'(u) = \text{notando f. } f'(0) = 0$$

$$f(u) = -\int_0^u \frac{\ln(1-u)}{u} du$$

mas a série primitiva i para $u=1 \rightarrow$

$$f(1) = -\int_0^1 \frac{\ln(1-u)}{u} du$$

n.º de calcul.

Funções elementares no campo complexo.

$$\text{Por definições } e^z = 1 + z + \frac{z^2}{2!} + \dots + \frac{z^n}{n!} + \dots = \sum_{n=0}^{\infty} \frac{z^n}{n!}$$

$$\cos z = 1 - \frac{z^2}{2!} + \frac{z^4}{4!} - \dots + \frac{(-1)^n z^{2n}}{(2n)!} + \dots$$

$$= \sum_{n=0}^{\infty} \frac{(-1)^n z^{2n}}{(2n)!}$$

$$\sin z = z - \frac{z^3}{3!} + \frac{z^5}{5!} - \dots + \frac{(-1)^n z^{2n+1}}{(2n+1)!} + \dots$$

$$= \sum_{n=0}^{\infty} \frac{(-1)^n z^{2n+1}}{(2n+1)!}$$

Estas definições podem ser dadas depois de se verificar que as séries são conv. em todo o plano complexo.

Desse def. res.:

$$\cos(-z) = \cos z$$

$$\sin(-z) = -\sin z$$

$$e^{iz} = \sum \frac{(iz)^n}{n!} = \sum \frac{(iz)^{2n}}{(2n)!} + \sum \frac{(iz)^{2n+1}}{(2n+1)!}$$

$$= \sum (-1)^n \frac{z^{2n}}{(2n)!} + i \sum (-1)^n \frac{z^{2n+1}}{(2n+1)!}$$

$$e^{iz} = \cos z + i \sin z$$

Mudando z em $-z \rightarrow$

$$e^{-iz} = \cos z - i \sin z$$

16.10.946

Dr. Ceruti

São conhecidos os operadores i e e^{ip} .
Componentes simétricas:

$$\alpha = e^{i \frac{2\pi}{n}}$$

para $n > 0$ (int.º)

$$\alpha^r = e^{i \frac{2\pi}{n} r} \text{ sendo } r \geq 0 \quad \underline{r \leq n}$$

$$\alpha^{-r} = e^{-i \frac{2\pi}{n} r} \text{ (sentido retrógrado de rotaç.º)}$$

Sequência de operadores de ordem n , de índice n se chama a um conj. de potências

$$S_n^p = \alpha^0, \alpha^{-1}, \alpha^{-2}, \alpha^{-3}, \dots, \alpha^{-(n-1)}$$

Q vetor a que aplicamos a sequência, se den. base de sequência \vec{b} .

$$\vec{b} = \alpha^0 \vec{b}, \alpha^{-1} \vec{b}, \alpha^{-2} \vec{b}, \dots$$

$$\alpha^n \vec{b} = \vec{b} \quad \text{Soma de sequências}$$

$$\text{Se } \alpha \neq 0 \rightarrow \sum_{n \neq 0} \alpha^n \vec{b} = 0$$

$$\text{e } \alpha = 0 \rightarrow \sum_{n=0} \alpha^n \vec{b} = n \vec{b}$$

Produtos de sequências de mesmo índice.

$$S_n^i \cdot S_n^p = S_n^{i+p}$$

$$S_n^{n+p} = S_n^n \cdot S_n^p = S_n^p$$

Caso mais comum: $n=3$

Se temos um sist. de n vetores coplanares de $\mathbb{R}^2 = \sum_{i=1}^n \vec{u}_i$ e é equiv. à soma de $(n-1)$ vetores de igual módulo e formando ângulos iguais.

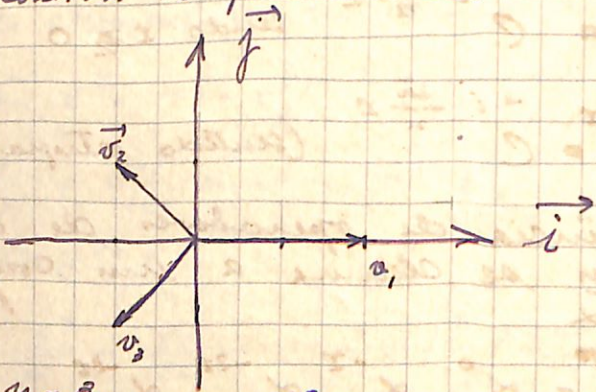
Se $\mathbb{R} \neq 0$ ter. μ a soma de n vetores.

Exemplo: -

Sejam dados: $\vec{v}_1 = 2\vec{i}$
 $\vec{v}_2 = -\vec{i} + \vec{j}$
 $\vec{v}_3 = -\vec{i} - \vec{j}$

Calcula o sistema equivalente de Componentes Metricas.

Eles estão contidos no primeiro caso, $\mathbb{R} = 0$



no caso $n=3$

$$S_3^1 = \alpha^0, \alpha^{-1}, \alpha^{-2}$$

$$S_3^2 = \alpha^0, \alpha^{-2}, \alpha^{-4}$$

no caso, $\alpha^0 = e^{i \frac{2\pi}{3}} = \cos 120^\circ + i \sin 120^\circ$
 $= -\frac{1}{2} + i \frac{\sqrt{3}}{2}$

$$\alpha^{-1} = e^{-i\varphi} = e^{-i \frac{2\pi}{3}} = -\frac{1}{2} - \frac{\sqrt{3}}{2} i = \alpha^2$$

$$\alpha^{-2} = -\frac{1}{2} + i \frac{\sqrt{3}}{2}$$

$$\alpha^{-4} = \alpha^{-1} = \frac{1}{2} - \frac{\sqrt{3}}{2} i$$

$$\vec{v}_i = \sum_{r=1}^2 \alpha^{(i-r)r} \vec{u}_r \quad (i=1,2,3)$$

$$i=1 \rightarrow \vec{v}_1 = \alpha^0 \vec{u}_1 + \alpha^0 \vec{u}_2 = 2\vec{i}$$

$$i=2 \rightarrow \vec{v}_2 = \alpha^{-1} \vec{u}_1 + \alpha^{-2} \vec{u}_2 = -\vec{i} + \vec{j}$$

$$i=3 \rightarrow \vec{v}_3 = \alpha^{-2} \vec{u}_1 + \alpha^{-4} \vec{u}_2 = -\vec{i} - \vec{j}$$

Façamos os coef. de \vec{u}_1 serem unitários:

$$\begin{aligned} 2\vec{i} &= \alpha^0 \vec{u}_1 + \alpha^0 \vec{u}_2 \\ -\vec{i} + \vec{j} &= \alpha^{-1} \vec{u}_1 + \alpha^{-2} \vec{u}_2 \\ 2\vec{i} - 2\vec{j} &= \alpha^{-2} \vec{u}_1 + \alpha^{-4} \vec{u}_2 \end{aligned}$$

mas $S_3^1 = \alpha^0, \alpha^{-1}, \alpha^{-2}$, portanto $\sum S_3^1 = 0$

formando membro a membro e aplicando α^1, α^2 nos vetores $\vec{i}, \vec{j}, \vec{k} \dots$

$$\begin{aligned} \alpha \vec{u}_1 &= 2\vec{i} + \frac{1}{2}\vec{i} - \frac{\sqrt{3}}{2}\vec{j} - \frac{1}{2}\vec{j} - \frac{\sqrt{3}}{2}\vec{i} + \frac{1}{2}\vec{i} + \frac{\sqrt{3}}{2}\vec{j} \\ &+ \frac{1}{2}\vec{j} - \frac{\sqrt{3}}{2}\vec{i} = (3-\sqrt{3})\vec{i} \\ \vec{u}_1 &= \left(1 - \frac{\sqrt{3}}{3}\right)\vec{i} \end{aligned}$$

$$\begin{aligned} \rho_3' \vec{u}_1 &= \alpha^0 \vec{u}_1 + \alpha^{-1} \vec{u}_1 + \alpha^{-2} \vec{u}_1 \\ &= \left(1 - \frac{\sqrt{3}}{3}\right) \vec{i}, -\frac{1}{2} \left(1 - \frac{\sqrt{3}}{3}\right) \vec{i} - i \frac{\sqrt{3}}{2} \left(1 - \frac{\sqrt{3}}{3}\right) \vec{i} \end{aligned}$$

22.10.1946.

Dr. Barros.

$$e^z = 1 + z + \frac{z^2}{2!} + \dots + \frac{z^n}{n!} + \dots$$

$$\cos z = 1 - \frac{z^2}{2!} + \frac{z^4}{4!} - \dots + (-1)^n \frac{z^{2n}}{2n!} + \dots$$

$$\sin z = z - \frac{z^3}{3!} + \frac{z^5}{5!} - \dots + (-1)^n \frac{z^{2n+1}}{(2n+1)!} + \dots$$

p. defin.

Das definições resulta

$$\cos z = \cos(-z) \quad \sin z = -\sin(-z)$$

$$\cos z + i \sin z = e^{iz}$$

$$\cos z - i \sin z = e^{-iz}$$

Destas relações resultam as fórmulas de Euler:

$$\cos z = \frac{e^{iz} + e^{-iz}}{2} \quad \sin z = \frac{e^{iz} - e^{-iz}}{2i}$$

A derivadas destas três funções e^z , $\cos z$ e $\sin z$, têm valores análogos ao do campo real.

C. efeito, derivando as séries correspondentes:

$$\frac{d}{dz} e^z = 1 + z + \frac{z^2}{2!} + \dots + \frac{z^{n-1}}{(n-1)!} + \dots = e^z$$

$$\frac{d}{dz} \cos z = -z + \frac{z^3}{3!} - \frac{z^5}{5!} + \dots = -\sin z$$

$$\frac{d}{dz} \sin z = 1 - \frac{z^2}{2!} + \frac{z^4}{4!} - \dots = \cos z$$

Para completar a analogia com o campo real, resta provar a propriedade:

Aplicando o teorema

$$e^z \cdot e^w = e^{z+w}$$

de produtos de séries, ou efetuando:

$$e^z e^w = \left(1 + z + \frac{z^2}{2!} + \dots + \frac{z^n}{n!} + \dots\right) \left(1 + w + \frac{w^2}{2!} + \dots + \frac{w^3}{3!} + \dots + \frac{w^u}{u!} + \dots\right) =$$

$$= (a_1 + a_2 + \dots + a_n + \dots) \quad \text{onde:}$$

$$a_1 = 1 \cdot 1 = 1 \quad a_2 = 1 \cdot w + z \cdot 1 \quad a_3 = \frac{1 \cdot w^2}{2!} + z \cdot w + \frac{z^2}{2!} \cdot 1$$

$$a_n = \frac{1 \cdot w^n}{n!} + \frac{z \cdot w^{n-1}}{(n-1)!} + \dots + \frac{z^i}{i!} \frac{w^{n-i}}{(n-i)!} + \dots + \frac{z^n}{n!} \cdot 1 =$$

$$= \sum_{i=0}^n \frac{1}{i!(n-i)!} \cdot w^{(n-i)} \cdot z^i = \sum_{i=0}^n \frac{1}{n!} \frac{n!}{i!(n-i)!} z^i w^{n-i}$$

$$= \frac{1}{n!} \sum_{i=0}^n \binom{n}{i} z^i w^{n-i} = \frac{(z+w)^n}{n!}$$

form. do Binom. de Newton

portanto, $e^z e^w = \sum \frac{(z+w)^n}{n!} = e^{z+w}$

Conseqüências:

$$\cos(z+w) = \cos z \cdot \cos w - \operatorname{sen} z \cdot \operatorname{sen} w$$

$$\operatorname{sen}(z+w) = \operatorname{sen} z \cdot \cos w + \cos z \cdot \operatorname{sen} w$$

$$\text{Ora, } \cos z \cdot \cos w = \frac{e^{iz} + e^{-iz}}{2} \cdot \frac{e^{iw} + e^{-iw}}{2} =$$

$$= \frac{1}{4} \left[e^{i(z+w)} + e^{-i(z+w)} + e^{i(z-w)} + e^{-i(z-w)} \right]$$

$$\operatorname{sen} z \cdot \operatorname{sen} w = \frac{e^{iz} - e^{-iz}}{2i} \cdot \frac{e^{iw} - e^{-iw}}{2i} =$$

$$= -\frac{1}{4} \left[e^{i(z+w)} + e^{-i(z+w)} - e^{i(z-w)} - e^{-i(z-w)} \right]$$

Por subtração:

$$\cos z \cdot \cos w - \operatorname{sen} z \cdot \operatorname{sen} w = \frac{1}{2} \left[e^{i(z+w)} + e^{-i(z+w)} \right] =$$

$$= \cos(z+w)$$

Verifica-se também que $\operatorname{sen} 0 = 0$, $\cos 0 = 1$

$$\operatorname{sen} \frac{\pi}{2} = \frac{e^{i\pi/2} + e^{-i\pi/2}}{2} = 1 \quad \cos \frac{\pi}{2} = 0$$

Podemos nestes casos igualar as séries de termos reais com as de termos imaginários, e supondo conhecidas as somas das de termos reais, temos as somas de termos imag.

Funções hiperbólicas.

Por definição: $\operatorname{sh} z = \frac{\operatorname{sen} iz}{i}$, ou,

aplicando a fórmula de Euler:

$$\operatorname{sh} z = \frac{1}{i} \frac{e^{i(iz)} - e^{-i(iz)}}{2i} = -\frac{1}{2} (e^{-z} - e^z) \rightarrow$$

$$\operatorname{sh} z = \frac{e^z - e^{-z}}{2}$$

e também p. defin.:

$$\operatorname{ch} z = \cos iz = \frac{e^{i(iz)} + e^{-i(iz)}}{2} =$$

$$= \frac{e^z + e^{-z}}{2}$$

Observação - Das defin. de sh e ch

resulta que - todas as fórmulas reais da Trigonometria hiperbólica obtêm-se

das formulas correspondentes de Trigon. Circulares substituindo-se

$$\cos = \frac{e^{ix} + e^{-ix}}{2} \text{ e } \sin = \frac{e^{ix} - e^{-ix}}{2i}$$

Seus vejamos:

$$\cos^2 x + \sin^2 x = 1$$

$$(ch x)^2 + (ish x)^2 = 1 \therefore ch^2 x - sh^2 x = 1$$

on
 $sh 2x = 2sh x \cdot ch x$

$$\frac{d}{dx} sh 2x = 2 ch x \cdot ch x$$

Derivadas -

Falta 2 aulas f. fin + pedm.

Provas que

$$\frac{x}{2} = 1 + \binom{\frac{1}{2}}{1} x + \binom{\frac{1}{2}}{2} x^2 + \binom{\frac{1}{2}}{3} x^3 + \dots$$

$$+ (-1)^{n-1} \binom{\frac{1}{2}}{n} \frac{1}{2n-1} + \dots$$

Consideremos a serie:

$$S(x) = 1 + \binom{\frac{1}{2}}{1} x + \binom{\frac{1}{2}}{2} x^2 + \binom{\frac{1}{2}}{3} x^3 + \dots$$

$$+ \dots + (-1)^{n-1} \binom{\frac{1}{2}}{n} \frac{x^{2n-1}}{2n-1}$$

Mas pela semelhancas com as series de potencia: $a_0 + a_1 x + a_2 x^2 + \dots$, temos

$$b_0 + b_1 x + b_2 x^3 + b_3 x^5 + \dots$$

$$= \frac{1}{x} [b_0 x + b_1 x^2 + b_2 x^3 + \dots] = \text{onde se}$$

Consideremos $x^2 = y \rightarrow \frac{1}{\sqrt{y}} [b_0 \sqrt{y} + b_1 y + b_2 y^2 + b_3 y^3 + \dots]$

é serie de potencia.

Qual o raio de convergência de serie pro.

$$\lim_{n \rightarrow \infty} \left| \frac{a_n}{a_{n+1}} \right| = \lim_{n \rightarrow \infty} \frac{\binom{\frac{1}{2}}{n} \frac{1}{2n-1}}{\binom{\frac{1}{2}}{n+1} \frac{1}{2n+1}} = \lim_{n \rightarrow \infty} \frac{\binom{\frac{1}{2}}{n}}{\binom{\frac{1}{2}}{n+1}} \cdot \frac{2n+1}{2n-1}$$

$$= \lim_{n \rightarrow \infty} \frac{n+1}{\frac{1}{2}-n} \cdot \frac{2n+1}{2n-1} = \lim_{n \rightarrow \infty} \frac{(1+\frac{1}{n})(2+\frac{1}{n})}{(1-\frac{1}{2n})(2-\frac{1}{n})} = 1$$

Portanto, a serie é definida no intervalo aberto $-1 < x < 1$, onde

ela é convergente, absoluta e uniformemente.

Derivemos-la -

$$S'(x) = \binom{\frac{1}{2}}{1} x - \binom{\frac{1}{2}}{2} x^2 + \binom{\frac{1}{2}}{3} x^3 + \dots + (-1)^{n-1} \binom{\frac{1}{2}}{n} x^{2n-2} + \dots$$

$$x^2 S'(x) = \binom{\frac{1}{2}}{1} x^2 - \binom{\frac{1}{2}}{2} x^4 + \dots + (-1)^{n-1} \binom{\frac{1}{2}}{n} x^{2n-1} + \dots =$$

$$= 1 - (1-x^2)^{1/2} \text{ pelo binomio de Newton.}$$

$$(1-x^2)^{1/2} = 1 - \binom{\frac{1}{2}}{1} x^2 + \binom{\frac{1}{2}}{2} x^4 + \dots$$

Portanto -

$$S'(x) = \frac{1 - (1-x^2)^{1/2}}{x^2} \text{ e por integraç.}$$

$$S(x) = \int_0^x \frac{1 - (1-t^2)^{1/2}}{t^2} dt = \int_0^x \frac{dt}{t^2} - \int_0^x \frac{\sqrt{1-t^2}}{t^2} dt =$$

$$= \left[\frac{1}{ie} \right]_{\theta}^{1e} - \left[-\cotg t \right]_{\theta}^t + 1$$

$$S(u) = -\frac{1}{ie} + \frac{(1-1e^2)^{1/2}}{e} + \operatorname{arcsen} u + 1 +$$

$$+ \lim_{1e \rightarrow 0} \left[\frac{1}{1e} - \frac{(1-1e^2)^{1/2}}{e} \right] =$$

$$= -1 + \frac{\pi}{2} + 1 =$$

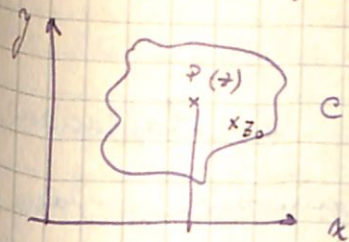
$$\boxed{= \frac{\pi}{2}}$$

cf)

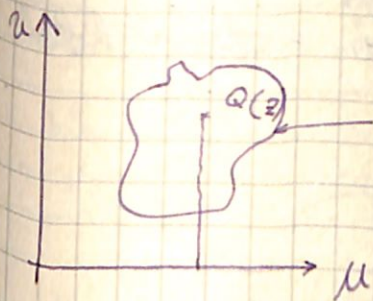
28.10.46

Funções complexas de variável complexa

D. Carr.



$$z = u + iv$$



$$z = f(z) = u + iv$$

$$u = u(u, v) \quad v = v(u, v)$$

$f(z)$ é cont. no ponto z_0 . Se:

$$\lim_{z \rightarrow z_0} f(z) = f(z_0)$$

Derivadas - idêntica defini.

$$\lim_{z \rightarrow z_0} \frac{f(z) - f(z_0)}{z - z_0} = \left(\frac{df}{dz} \right)_{z=z_0} \quad z \rightarrow z_0 \text{ de } \mathbb{C} \text{ ou } \mathbb{R}$$

Teor. imp.^a :- (parte vaga do exame)

As cond. nec. e suf. p. haver a deriv. são -

1) $f(z)$ seja definida no ponto

2) $f(z)$ " cont. " " "

3) $\frac{\partial u}{\partial x}$ $\frac{\partial v}{\partial y}$ $\frac{\partial x}{\partial y}$ $\frac{\partial u}{\partial x}$ existam e sejam cont.

$$4) \frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} \quad \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$$

Se a fç. satisfaz a estas 4 cond. ela é chamada holomorfa.

u e v são harmônicas.

$$\Delta_2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \quad \text{é o laplaciano, se}$$

$\Delta_2 u$ é nula, a fç. u é harmônica. Idem para v .
Se u e v forem harmônicas, a fç. é holomorfa.

Problemas -

① Dada $f(z)$, verificar se é holomorfa; e se suas componentes são harmônicas, pseudo holomorfa.

② Construir uma função holomorfa $f(z)$, dada uma das componentes, u ou v .
Devemos achar v ou u . (Estudar!)

Exercícios: -

Dada - $z^3 - 3z^2 - z = f(z)$

$z = u + iy$, verif. se é holomorfa.

$$z^2 = u^2 + 2iuy - y^2$$

$$z^3 = u^3 + 3i u^2 y + 3u y^2 + i u^2 y^2 - 3u y^2$$

$$f(z) = u^3 + 3i u^2 y - 3u y^2 + i u^2 y^2 - 3u y^2 - iy - (3u^2 + 6iuy - 3y^2) - u - iy =$$

$$u^3 - 3u y^2 - 3u^2 + 3y^2 - 1$$

$$= 3u^2 y - y^3 - 6u y - y$$

$$u'_x = 3u^2 - 3y^2 - 6x - 1$$

$$u'_y = -6xy + 6y$$

$$u'_x = 6xy - 6y$$

$$u'_y = 3x^2 - 3y^2 - 6x - 1$$

veja-se se são harmônicas -

$$u''_x = 6x - 6 \quad u''_x$$

$$u''_y = -6x + 6 \quad u'_y$$

Artificiais

Seja $f(z) = \frac{1}{z}$ $z = x + iy$

$$\frac{1}{z} = \frac{1}{x + iy} = u + iv$$

$$\frac{x - iy}{x^2 + y^2} = u + iv$$

$$u = \frac{x}{x^2 + y^2} \quad v = \frac{-y}{x^2 + y^2}$$

$$f(z) = \sqrt{z} = \sqrt{u + iy} = u + iv$$

elevando ao quadrado,
 $u + iy = u^2 - v^2 + 2iuv$

$$u = u^2 - v^2 \quad y = 2uv$$

daqui tiramos u e v .

$$f(z) = lz = l(u + iv)$$

$$e^{f(z)} = (u + iv) = z \quad \text{pela exponencial.}$$

$$e^{u+iv} = e^u \cdot e^{iv} = e^u (\cos v + i \sin v) = u + iv =$$

portanto:

$$\left. \begin{aligned} e^u \cos v &= u \\ e^u \sin v &= v \end{aligned} \right\} \text{div. } \tan v = \frac{v}{u}$$

$$v = \arctg \frac{v}{u}$$

elevando ao quadrado e somando -

$$e^{2u} = u^2 + v^2 \quad u = \frac{l(u^2 + v^2)}{2}$$

② Construção de função hol.

Dá. $h: u(x, y) = x^3 - 3xy^2 + 3x^2 - 3y^2 + 1$

$$\frac{\partial u}{\partial x} = 3x^2 - 3y^2 + 6x = \frac{\partial v}{\partial y}$$

integrando: $v = 3x^2y - y^3 + 6xy + \varphi(x)$

mas $\frac{\partial u}{\partial y} = -6xy - 3y^2 = -\frac{\partial v}{\partial x} =$

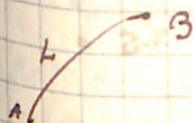
$$= -[6xy + 3y^2 + \varphi'(x)]$$

portanto $\varphi'(x) = 0 \rightarrow \varphi(x) = c$

e vem: $f(z) = z^3 + 3z^2 + c$

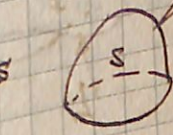
29.10.945

Circunferência - Dado $\vec{v}(P)$ definido na linha L , circ. e $I = \int_L \vec{v}(P) \times dP$



Se tivermos uma superfície -

$$\text{Fluxo } \phi = \iint_S \vec{v} \times \vec{n} \, dS$$



Teorema de Gauss -

$$\iiint_V \text{div } \vec{v} \, dV = \iint_S \vec{v} \times \vec{n} \, dS$$

convenção - se fluxo positivo (para dentro é a / preceito do sinal +), de dentro para fora.

$$\vec{v} = P\vec{i} + Q\vec{j} + R\vec{k}$$

$$\text{div } \vec{v} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

temos a expressão cartesiana -

$$\iiint_V \left(\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right) dV = \iint_S (P \cos \alpha + Q \cos \beta + R \cos \gamma) dS$$

$$= \iint_S P dy dz + Q dz dx + R dx dy$$

Caso partic. : $Q = R = 0$

$$\iiint_V \frac{\partial P}{\partial x} dV = \iint_S P dy dz \quad \text{se } P = x$$

$$V = \iiint_S x \, dy \, dz$$

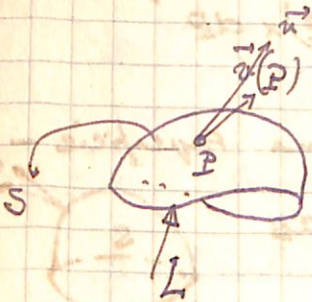
$$V = \iint_S y \, dx \, dz \quad \dots$$

de man. idêntica -

portanto - $V = \frac{1}{3} \iint_S (x \cos \alpha + y \cos \beta + z \cos \gamma) ds$

Fezemos o elemento da transformação de integrais de vol. em int. de superf.

Teor. de Stokes -



$$\iint_S \text{rot } \vec{v} \times \vec{n} \cdot d\vec{s} = \int_L \vec{v} \cdot d\vec{r}$$

↑
circulação.

Expressão cartesiana -

$$\vec{v} = P\vec{i} + Q\vec{j} + R\vec{k}$$

$$\text{rot } \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix}$$

portanto:

$$\iint_S \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} \times \vec{n} \cdot d\vec{s} =$$

$$= \int_L (P\vec{i} + Q\vec{j} + R\vec{k}) \times d\vec{r}$$

$$\iint_S \begin{vmatrix} \cos \alpha & \cos \beta & \cos \gamma \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} ds = \int_L P dx + Q dy + R dz$$

Após no Dep. Mat. (Dr. Ceruti)
o sist. de vetores $\vec{v}_1 = 2\vec{i} - \vec{j}$, $\vec{v}_2 = -\vec{i} + \vec{j}$, $\vec{v}_3 = -\vec{i}$
o sistema de componentes simétricas.

Result. do sist.: $\vec{R} = \sum \vec{v}_i = 0$
Ex. 1. pg. 41. No. 33 Calc. vetorial - a result. sendo
o sistema por a soma de 2 sequências de

$$S_3^1 \vec{u}_1, S_3^2 \vec{u}_2$$

Calc. dos vetores bases \vec{u}_1, \vec{u}_2 : $\vec{u}_i = \sum_{r=1}^2 \alpha^{(i-r)} \vec{v}_r$
Formamos o sist. de eq.

$$\begin{cases} 2\vec{i} - \vec{j} = \alpha^0 \vec{u}_1 + \alpha^0 \vec{u}_2 & (1) \\ -\vec{i} + \vec{j} = \alpha^{-1} \vec{u}_1 + \alpha^{-2} \vec{u}_2 & (2) \\ -\vec{i} = \alpha^{-2} \vec{u}_1 + \alpha^{-4} \vec{u}_2 & (3) \end{cases}$$

Operando à esquerda
respectivamente com
dois membros de (2) e de (3)
operadores α^{-1}, α^{-2} , vem:

$$\begin{cases} 2\vec{i} - \vec{j} = \vec{u}_1 + \vec{u}_2 & (1) \\ \alpha^{-1}(-\vec{i} + \vec{j}) = \alpha^{-1} \vec{u}_1 + \alpha^{-3} \vec{u}_2 & (2) \\ \alpha^{-2}(-\vec{i}) = \alpha^{-2} \vec{u}_1 + \alpha^{-6} \vec{u}_2 & (3) \end{cases}$$

Tomando membro a membro e observando que
última coluna da soma nula, obtemos:

$$\begin{aligned} 3\vec{u}_1 &= 2\vec{i} - \vec{j} + \alpha(-\vec{i} + \vec{j}) - \alpha^2 \vec{i} \\ \alpha &= e^{i\frac{2\pi}{3}} = \cos 120^\circ + i \sin 120^\circ = -\frac{1}{2} + i\frac{\sqrt{3}}{2} \\ \alpha^2 &= \alpha^{-1} = \cos 120^\circ - i \sin 120^\circ = -\frac{1}{2} - i\frac{\sqrt{3}}{2} \end{aligned}$$

Multiplicando, vem:

$$3\vec{u}_1 = (2\vec{i} - \vec{j}) + \left(-\frac{1}{2} + i\frac{\sqrt{3}}{2}\right)(-\vec{i} + \vec{j}) - \left(-\frac{1}{2} - i\frac{\sqrt{3}}{2}\right)\vec{i}$$

$$= 2\vec{i} - \vec{j} + \frac{1}{2}\vec{i} - \frac{1}{2}\vec{j} - \frac{\sqrt{3}}{2}\vec{j} - \frac{\sqrt{3}}{2}\vec{i} + \frac{1}{2}\vec{i} + \frac{\sqrt{3}}{2}\vec{j}$$

$$= \left(3 - \frac{\sqrt{3}}{2}\right)\vec{i} + \frac{3}{2}\vec{j} \rightarrow \vec{u}_1 = \left(1 - \frac{\sqrt{3}}{6}\right)\vec{i} - \frac{1}{2}\vec{j}$$

De (1) tiramos $\vec{u}_2 = (2\vec{i} - \vec{j}) - \left(1 - \frac{\sqrt{3}}{6}\right)\vec{i} + \frac{1}{2}\vec{j} =$

$$= (1 + \sqrt{3}/6) \vec{i} - \frac{1}{2} \vec{j} \rightarrow \boxed{\vec{u}_2 = (1 + \frac{\sqrt{3}}{6}) \vec{i} - \frac{1}{2} \vec{j}}$$

4) Sequência de vetores $S_3^1; S_3^2$

A. $S_3^1 = \alpha^0, \alpha^{-1}, \alpha^{-2} = 1, \alpha^2, \alpha$
(seq. de fase negat. ou sim. inversa)
no 32 pg. 41, in fine.

$$\begin{cases} \vec{u}_1 = (1 - \sqrt{3}/6) \vec{i} - \frac{1}{2} \vec{j} \\ \alpha^2 \vec{u}_1 = (-\frac{1}{2} - i \frac{\sqrt{3}}{2}) \vec{u}_1 = (-\frac{1}{2} + \sqrt{3}/6) \vec{i} - (\sqrt{3}/2) \vec{j} \\ \alpha \vec{u}_1 = (-\frac{1}{2} + i \frac{\sqrt{3}}{2}) \vec{u}_1 = (-\frac{1}{2} - \sqrt{3}/6) \vec{i} + \sqrt{3}/2 \vec{j} \end{cases}$$

Verifica çõ: $\vec{u}_1 + \alpha^2 \vec{u}_1 + \alpha \vec{u}_1 = 0$

B. $S_3^2 = \alpha^0, \alpha^{-2}, \alpha^{-1} = 1, \alpha, \alpha^{-1} = 1, \alpha, \alpha^{-2}$
(seq. de fase posit. ou sim. direta)

$$\begin{cases} \vec{u}_2 = (1 + \sqrt{3}/6) \vec{i} - \frac{1}{2} \vec{j} \\ \alpha \vec{u}_2 = (-\frac{1}{2} + i \sqrt{3}/2) \vec{u}_2 = (-\frac{1}{2} - \sqrt{3}/6) \vec{i} + (\sqrt{3}/2) \vec{j} \\ \alpha^2 \vec{u}_2 = (-\frac{1}{2} - i \sqrt{3}/2) \vec{u}_2 = (-\frac{1}{2} + \sqrt{3}/6) \vec{i} - \sqrt{3}/2 \vec{j} \end{cases}$$

Verific.: $\vec{u}_2 + \alpha \vec{u}_2 + \alpha^2 \vec{u}_2 = 0$

Dado o sist. de vetores $\vec{v}_1 = 2\vec{i}, \vec{v}_2 = -2\vec{i} + \vec{j}; \vec{v}_3 = -\vec{i} - \vec{j}$ calcular suas componentes simétricas.
Sol. -

Aplicações -

Calcular a circunferência do vetor

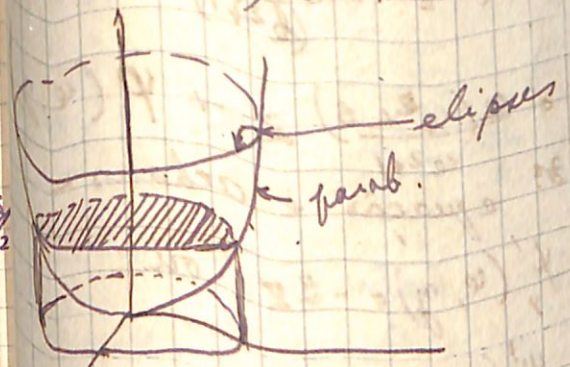
$$\vec{r}(P) = (y-1) \vec{i} + (2x+1) \vec{j} + 2\vec{k} \text{ ao longo da linha } L = \begin{cases} P = 0 + t\vec{i} + y\vec{j} + (\frac{x^2}{2} + \frac{y^2}{4})\vec{k} \\ y^2 + 2x^2 = 4 \end{cases}$$

$$I = \int_L \vec{v} \times dP = \iint_S \text{rot } \vec{v} \times \vec{n} \, ds$$

$$\text{rot } \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ (y-1) & (2x+1) & 2 \end{vmatrix} = \vec{k}(2-1) = \vec{k}$$

$$\vec{n} = \frac{P'_x \wedge P'_y}{|P'_x \wedge P'_y|}$$

$$\vec{n} = \vec{k}$$



(observar a interseção das duas superfícies e considerar a melhor das superfícies - elipse plana)

Portanto - $I = \iint_S dx dy = \int_0^{\sqrt{2}} dx \int_0^{2\sqrt{1-x^2}} dy = \pi a b = 2\pi \sqrt{2}$

Expressão $I = \iint_S \frac{x(x^2+3)}{x^2+1} \cos \alpha + \frac{2x^2y(x^2+3)}{(x^2+1)} \cos \beta - 3z \cos \gamma \, ds$ extendida a S , delimitada por L , por uma integral de forma - $J = \int_L P(x, y, z) dx + Q(x, y, z) dy + R(x, y, z) dz$ e calc. pf valor no caso partic.

em f. $L = x^2 + y^2 = 1$, situada no plano $z=1$.

pelo teor^a de Stokes -

$$\iint_S \begin{vmatrix} \cos \alpha & \cos \beta & \cos \gamma \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{vmatrix} ds = \int_L P dx + Q dy + R dz$$

$$= \int_L P dx + Q dy$$

Daqui tiramos, igualando os coef. de $\cos \alpha$, $\cos \beta$, $\cos \gamma$.

$$\textcircled{1} \quad -\frac{\partial Q}{\partial z} = \frac{u(u^2+3)}{u^2+1}$$

$$\textcircled{2} \quad \frac{\partial P}{\partial z} = \frac{2x^2 y (u^2+3)}{(u^2+1)^2}$$

$$\textcircled{3} \quad \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} = -3z$$

$$P = + \int \frac{2x^2 y (u^2+3)}{(u^2+1)^2} dz = \frac{2x^2 y (u^2+3)}{(u^2+1)^2} z + \psi(u, y)$$

$$Q = - \int \frac{u(u^2+3)}{u^2+1} dz + \varphi(u, y)$$

vamos agora à 3^a equação e achamos -

$$-3z + \varphi'_x(u, y) - \psi'_y(u, y) = -3z \quad \text{ou}$$

$$\varphi'_x(u, y) = \psi'_y(u, y)$$

Determinar uma função u de u , sendo

$$u = \frac{x^2 + y^2 - 1}{u} \quad \text{e uma f. } v \text{ de } v = \frac{x^2 + y^2 + 1}{y}$$

de maneira f. $U + iV$ seja holomorfa de

$$z = u + iy$$

Ora, U e V devem ser harmônicas, logo -

$$\Delta_2 U = \Delta_2 V = 0$$

$$\frac{dU}{dx} = \frac{dU}{du} \frac{\partial u}{\partial x} \quad \frac{d^2 U}{dx^2} = \frac{dU}{du} \frac{\partial^2 u}{\partial x^2} + \frac{d^2 U}{du^2} \left(\frac{\partial u}{\partial x} \right)^2$$

$$\frac{d^2 U}{dy^2} = \frac{dU}{du} \frac{\partial u}{\partial y} \quad \frac{d^2 U}{dy^2} = \frac{dU}{du} \frac{\partial^2 u}{\partial y^2} + \frac{d^2 U}{du^2} \left(\frac{\partial u}{\partial y} \right)^2$$

$$U''_x = U' u''_x + U'' (u'_x)^2$$

$$U''_y = U' u''_y + U'' (u'_y)^2$$

$$U''_x + U''_y = 0 \quad \text{ou}$$

$$U' (u''_x + u''_y) + U'' (u'^2_x + u'^2_y) = 0$$

$$\frac{U''}{U'} = - \frac{u'_x + u'_y}{u'^2_x + u'^2_y}$$

$$u'_x = \frac{x^2 - y^2 + 1}{x^2}$$

$$u''_x = \frac{2(y^2 - 1)}{x^3}$$

$$u'_y = \frac{2y}{x} \quad u''_y = \frac{2}{x}$$

$$u''_x + u''_y = \frac{2u}{x^2}$$

$$u''_x + u''_y = \frac{u^2 + 4}{x^2}$$

$$\frac{U''}{U'} = - \frac{2u}{u^2 + 4}$$

$$U' = \frac{dU}{dt} = t \quad U'' = t'$$

$$\frac{t'}{t} = - \frac{2u}{u^2 + 4}$$

$$dt = - \ln(u^2 + 4) + C =$$

$$= \ln \frac{C}{u^2 + 4}$$

$$U = \int t dt = C \int \frac{du}{u^2 + 4}$$

$$t = \frac{C}{u^2 + 4} \quad \frac{C}{2} \int \frac{1/2 du}{1 + \left(\frac{u}{2}\right)^2} = \frac{C}{2} \arctg \frac{u}{2} + C_1$$

~~At~~ De man? idêntica chegamos a:

$$V = \frac{c_1}{2} \cdot f \frac{v-2}{v+2} + C_2$$

$$c_4$$

Devemos agora aplicar as condições de Riemann - Cauchy:

$$\frac{\partial U}{\partial x} = \frac{\partial V}{\partial y}$$

$$\frac{\partial U}{\partial y} = -\frac{\partial V}{\partial x} \quad \text{para podermos calcular}$$

as constantes C_1, C_2, C_3 e C_4

Chegamos, efetuando os cálculos a

$$\text{que: } C_1 = C_2 \quad \text{e}$$

$$C_3 = C_4.$$

Da. se $u + v = z^3 - 3zy^2 - y^3 + 3x^2y$ $f(z) = u + iv$
 e pede-se u e v de maneira que $f(z)$ seja holomorfa.
 ($z = x + iy$) seja holomorfa.

Seja $U = u + v$ $V = u - v$ determinemos V ,
 onde U e depois calculemos u e v .

Da, $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$

e $u = U - v$ donde -
 $\frac{\partial U}{\partial x} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x}$ c) $\frac{\partial V}{\partial x} = \frac{\partial u}{\partial x} - \frac{\partial v}{\partial x}$

d) $\frac{\partial U}{\partial y} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial y}$ d) $\frac{\partial V}{\partial y} = \frac{\partial u}{\partial y} - \frac{\partial v}{\partial y}$

Comparando (a) e (d): $a + d = 0$

$\left\{ \frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} = 0 \right.$; b com $c \rightarrow b - c = 0$

$\left. \frac{\partial U}{\partial y} - \frac{\partial V}{\partial x} = 0 \right.$

$$\frac{\partial U}{\partial x} = 2x^2 - 2y^2 + 6xy = -\frac{\partial V}{\partial y}$$

Integrando -
 $-V = 2yx^2 - \frac{2y^3}{3} + 6xy \frac{y^2}{2} + \varphi(x)$

~~at~~ $\frac{\partial V}{\partial x} = -6xy + 2y^2 + \varphi'(x) = \frac{\partial U}{\partial y}$
 $= -6xy - 2y^2 + 2x^2$

portanto $\varphi'(x) = -3x^2 \rightarrow \varphi(x) = -x^3 + c$

e $V = -2yx^2 + y^3 + 2y^2 + x^3 + c = u - v$

$$U = z^3 - 3zy^2 - y^3 + 3x^2y = u + v$$

formando:

$$2u = 2x^3 + 2y^2 - 2zy^2 + c$$

$$u = \frac{1}{2} \left[2x^3 + 2y^2(1 - z) + c \right]$$

7.11.46

Calcular $I = \int \frac{dz}{1+z^3}$ $z = x+iy$

longo da elipse $2x^2 + y^2 = 2$

Aplica-se o teora de Cauchy -

$f(z)$ sendo $f(z)$ holom. nos pontos do contorno e no interior. $\int_C f(z) dz = 2\pi i \sum R(a_s)$

Polos são pontos onde a $f(z)$ se torna infinita. Se o polo é simples - $R(a_s) = \lim_{z \rightarrow a_s} (z - a_s) \cdot f(z)$

No nosso caso - $z^3 + 1 = 0$ nos 3 polos.

$$z^m + 1 = 0$$

$$z = \cos \left(\frac{2k+1}{m} \pi \right) + i \operatorname{sen} \left(\frac{2k+1}{m} \pi \right)$$

$$= e^{i \left(\frac{2k+1}{m} \pi \right)}$$

$$m=3 \begin{cases} k=0 \\ k=1 \\ k=2 \end{cases}$$

$$z^I = \cos 60^\circ + i \operatorname{sen} 60^\circ = \frac{1}{2} + i \frac{\sqrt{3}}{2}$$

$$z^{II} = \cos \pi + i \operatorname{sen} \pi = -1$$

$$z^{III} = \cos \frac{5\pi}{3} + i \operatorname{sen} \frac{5\pi}{3} = \frac{1}{2} - i \frac{\sqrt{3}}{2}$$

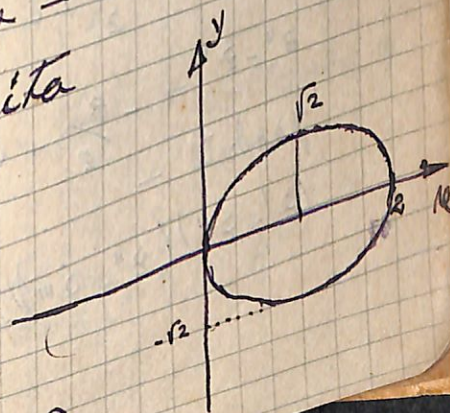
Para estes valores -

$$\int_C \frac{dz}{1+z^3} \text{ é infinita}$$

Escolhamos o

contorno -

$$x=0 \quad y=0 \quad x=\frac{1}{2} \quad y=\frac{\sqrt{3}}{2}$$



Estes valores correspondem a polos interiores à helipse.

Aplicamos o teorema de Cauchy:

$$I = \int_C \frac{dz}{1+z^3} = 2\pi i \sum R(z', z'')$$

$$R(z') = \lim_{z \rightarrow z'} \left(\frac{z-z'}{z^3-1} \right) =$$

$$= \lim_{z \rightarrow z'} \frac{z-z'}{(z-z')(z-z'')(z-z''')} = \frac{1}{(z'-z'')(z'-z''')}$$

$$R(z''') = \frac{1}{(z'''-z')(z'''-z'')}$$

$$\sum R = \frac{(z'-z''') + (z'-z'')}{(z'-z'')(z'-z''')(z'-z''')} =$$

$$= \frac{z'-z''}{(z'-z''')(z'-z'')(z''-z''')} = \frac{1}{(z'-z'')(z''-z''')}$$

$$z'-z'' = -\frac{1}{2} + i \frac{\sqrt{3}}{2}$$

$$z''-z''' = -\frac{3}{2} + i \frac{\sqrt{3}}{2} \text{ efetuando o}$$

produto -

$$(z'-z'')(z''-z''') = \frac{3}{4} - \frac{3}{4} \cdot \sqrt{3} i - \frac{\sqrt{3}}{4} \cdot i - \frac{3}{4} =$$

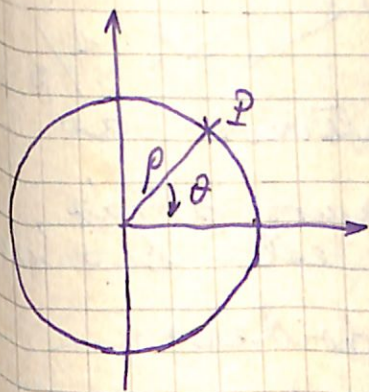
$$-i\sqrt{3} \text{ part}^2 - \sum R = \frac{1}{i\sqrt{3}} = \frac{i\sqrt{3}}{3}$$

$$I = 2\pi i \cdot \frac{\sqrt{3}}{3} i = \boxed{-\frac{2\pi\sqrt{3}}{3}}$$

Calcular -

$$I = \int_0^{2\pi} \frac{d\theta}{1-2p \cos \theta + p^2} \quad 0 < p < 1$$

para integrar, consideremos um círculo de raio 1, sobre o plano de Argand e um ponto $P(z = u + iy)$ dentro do círculo.



Então -

$$z = u + iy = \rho e^{i\theta} = \rho(\cos \theta + i \sin \theta)$$

$$\left\{ \begin{array}{l} \rho = 1 \\ z = e^{i\theta} \quad dz = i e^{i\theta} d\theta \end{array} \right.$$

$$d\theta = \frac{dz}{iz}$$

$$\left\{ \begin{array}{l} z = \cos \theta + i \sin \theta \\ z^{-1} = \cos \theta - i \sin \theta \end{array} \right\} \text{ de qui -}$$

$$\cos \theta = \frac{1}{2} \left(z + \frac{1}{z} \right) \text{ voltando a}$$

$$\text{integral - } I = \int_C \frac{dz}{iz \left[1 - 2p \cdot \frac{1}{2} \left(z + \frac{1}{z} \right) + p^2 \right]} =$$

$$= -i \int_C \frac{dz}{p z^2 + \overline{p}(z^2+1) + p} \text{ e caímos}$$

na integral do exercício anterior - aplicamos o teorema de Cauchy -

$$I = 2\pi i \sum R(a_s)$$

Vejam os polos -

$$z = \frac{p^2+1 \pm \sqrt{(p^2+1)^2 - 4p^2}}{2p}$$

$$= \frac{p^2+1 \pm (p^2-1)}{2p} \begin{cases} z' = p \\ z'' = 1/p \end{cases}$$

Vejam se são internos ao círculo que consideramos atrás, ora, $p < 1$, logo este é o único polo que devemos considerar -

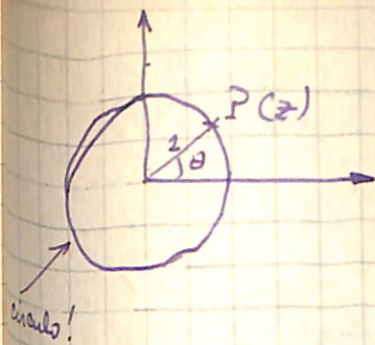
$$R(z) = \lim_{z \rightarrow p} \frac{(z-p)}{p(z-p)(z-\frac{1}{p})} = \frac{1}{p^2-1}$$

logo -

$$I = \frac{2\pi i \cdot i}{p^2-1} = \frac{2\pi}{1-p^2}$$

Calcular $I = \int_0^{2\pi} \frac{a d\theta}{a^2 + p \cos^2 \theta}$ $a > 0$

ora $I = \frac{1}{2} \int_0^{2\pi} \frac{a d\theta}{a^2 + \sin^2 \theta}$ \checkmark se $a < 1$, é pa



$$z = e^{i\theta} = \cos \theta + i \sin \theta$$

$$dz = e^{i\theta} i d\theta$$

$$d\theta = \frac{dz}{iz}$$

$$z - \frac{1}{z} = 2i \sin \theta$$

$$\sin^2 \theta = \frac{(z^2-1)^2}{4z^2}$$

$$= -\frac{(z^2-1)^2}{4z^2}$$

volvendo a integral -

$$I = \frac{1}{2} \int_C \frac{a dz}{iz \left[a^2 - \frac{(z^2-1)^2}{4z^2} \right]}$$

$$= \frac{4a}{2i} \int \frac{z dz}{4a^2 z^2 - (z^2-1)^2}$$

resolvendo a equação biquadrada que aparece no denominador, obtemos 4 polos -

$$z' = -a + m \quad z'' = -a - m \quad z''' = a + m$$

$$z'' = a - m \quad a = \sqrt{a^2 - 1}$$

Só ~~dois~~ caem dentro do círculo os polos de z' e z''

Portanto -

$$R(z') = \lim_{z \rightarrow z'} \frac{(z-z') f'(z)}{f(z)}$$

$$= -\frac{1}{2m}$$

$$R(z'') = \dots = -\frac{1}{2m}$$

$$I = 2\pi i \cdot \frac{4a}{2i} \left(-\frac{1}{2m} - \frac{1}{2m} \right) e$$

$$= \frac{\pi}{\sqrt{a^2+1}}$$

Ar. Breves.
Séries de funções complexas

Provar que

$$1 - \frac{1}{5} + \frac{1}{7} - \frac{1}{11} + \frac{1}{13} - \frac{1}{17} + \dots = \frac{\pi}{2\sqrt{3}}$$

$$f(z) = z - \frac{z^5}{5} + \frac{z^7}{7} - \frac{z^{11}}{11} + \frac{z^{13}}{13} - \frac{z^{17}}{17} + \dots$$

será nossa série auxiliar.

$$f'(z) = (1 - z^4) + (z^6 - z^{10}) + (z^{12} - z^{16}) + \dots$$

$$f'(z) = (1 - z^4) (1 + z^6 + z^{12} + \dots)$$

cujo raio de convergência é 1 \rightarrow

R. $\lim_{n \rightarrow \infty} \left| \frac{a_n}{a_{n+1}} \right| = 1$, isto quer dizer que a série é convergente no intervalo $-1 \leq z \leq 1$

$$f'(z) = (1 - z^4) \frac{1}{1 - z^6} = \frac{1 + z^2}{1 + z^2 + z^4}$$

portanto - $f(z) = \int \frac{1 + z^2}{z^4 + z^2 + 1} dz$

$$\frac{1 + z^2}{1 + z^2 + z^4} = \frac{1 + z^2}{(1 + z + z^2)(1 + z + z^2)}$$

$$\frac{1}{2} \cdot \frac{(1 - z + z^2) + (1 + z + z^2)}{(1 - z + z^2) \cdot (1 + z + z^2)}$$

$$f(z) = \frac{1}{2} \int \frac{dz}{1 - z + z^2} + \frac{1}{2} \int \frac{dz}{1 + z + z^2} + c$$

$$= \frac{1}{2} \sqrt{\frac{4}{3}} \operatorname{arctg} \sqrt{\frac{4}{3}} \left(z - \frac{1}{2} \right) + \frac{1}{2} \sqrt{\frac{4}{3}} \operatorname{arctg} \sqrt{\frac{4}{3}} \left(z + \frac{1}{2} \right) + c$$

$$= \frac{1}{\sqrt{3}} \left[\operatorname{arctg} \frac{2z-1}{\sqrt{3}} + \operatorname{arctg} \frac{2z+1}{\sqrt{3}} \right] + c$$

ora, $f(0) = 0$ donde

$$f(0) = \frac{1}{\sqrt{3}} \left[\operatorname{arctg} \left(-\frac{1}{\sqrt{3}} \right) + \operatorname{arctg} \frac{1}{\sqrt{3}} \right] + c = 0$$

$$c = 0$$

portanto $f(z) = \frac{1}{\sqrt{3}} \left[\operatorname{arctg} \frac{2z-1}{\sqrt{3}} + \operatorname{arctg} \frac{2z+1}{\sqrt{3}} \right]$

$$\lim_{z \rightarrow 1} f(z) = \frac{1}{\sqrt{3}} \left(\operatorname{arctg} \frac{1}{\sqrt{3}} + \operatorname{arctg} \frac{3}{\sqrt{3}} \right) =$$

$$= \frac{1}{\sqrt{3}} \left(\operatorname{arctg} \frac{1}{\sqrt{3}} + \operatorname{arctg} \sqrt{3} \right) = \frac{1}{\sqrt{3}} \cdot \frac{\pi}{2} \text{ (cf.)}$$

Desenvolver em série -

$$f(z) = \ln \sqrt{1 + z^2} \quad f'(z) = \frac{2z}{2(\sqrt{1+z^2})^2} =$$

$$= \frac{z}{1+z^2} = z \frac{1}{1+z^2}$$

$$= z \frac{1 - (-z^2)^n + (-z^2)^n}{1 - (-z^2)} \text{ ora, } \frac{1-t^n}{1-t} = 1 + t + t^2 + \dots + t^{n-1}$$

$$f'(z) = z \left[1 + (-z^2) + (-z^2)^2 + (-z^2)^3 + \dots + (-z^2)^{n-1} \right] + \frac{(-z^2)^n}{1 - (-z^2)}$$

$$= z \left[1 - z^2 + z^4 - z^6 + \dots + (-1)^{n-1} z^{2(n-1)} \right] + \frac{(-1)^n z^{2n+1}}{1+z^2}$$

para $|u| < 1$ -

$$\lim_{n \rightarrow \infty} R_n = \lim_{n \rightarrow \infty} (-1)^n \frac{u^{2n+1}}{1+u^{2n}} = 0$$

portanto - $f'(u) = u - u^3 + u^5 - \dots$

O raio de convergência de $f'(u)$ é 1, então

$$f(u) = \frac{u^2}{2} + \frac{u^4}{4} + \frac{u^6}{6} + \dots$$

$f(0) = 0 = c$ portanto -

$$\ln \sqrt{1+u^2} = \frac{u^2}{2} - \frac{u^4}{4} + \frac{u^6}{6} - \frac{u^8}{8} + \frac{u^{10}}{10} - \dots$$

Desenvolver em série -

$f(u) = \cos^2 u$ $f'(u) = -2 \cos u \operatorname{sen} u = -\operatorname{sen} 2u$

Ora, $\operatorname{sen} t = a_0 + a_1 t + a_2 t^2 + \dots + a_n t^n + \dots$ deriva

$\cos t = a_1 + 2a_2 t + 3a_3 t^2 + \dots + n a_n t^{n-1} + \dots$

$-\operatorname{sen} t = 2a_2 + 2 \cdot 3 a_3 t + 3 \cdot 4 a_4 t^2 + \dots + n(n+1) a_{n+1} t^n + \dots$

Ora - $\operatorname{sen} t = -(-\operatorname{sen} t)$ portanto -

$a_0 = 2a_2$

$a_1 = 2 \cdot 3 a_3$

$a_2 = 3 \cdot 4 a_4$

$a_3 = \dots$

$\operatorname{sen} 0 = 0 = a_0$

$\cos 0 = 1 = a_1$

$a_0 = 0 = a_2, a_4, a_6, a_8 \dots$

$a_1 = -a_3 \times 6$

$a_1 = -2 \cdot 3 \cdot a_3$

$a_3 = -4 \cdot 5 a_5$

$a_{n-2} = -(n-1) \cdot n \cdot a_n$

$a_1 = -n! \cdot a_n = 1$ logo - $a_n = \frac{(-1)^{n-1}}{n!}$

$\operatorname{sen} t = t - \frac{1}{3!} t^3 + \frac{1}{5!} t^5 - \dots$ portanto -

$\operatorname{sen} 2x = -2x^3 + \frac{2^3}{3!} x^5 - \frac{2^5}{5!} x^7 + \dots$

integrando -

$\cos^2 u = -\frac{u^2}{4} + \frac{2^3}{4!} u^4 - \frac{2^5}{6!} u^6 + \dots$

$f(0) = 1 = c$ donde -

$\cos^2 u = 1 - \frac{u^2}{4} + \frac{2^3}{4!} u^4 - \frac{2^5}{6!} u^6 + \dots$

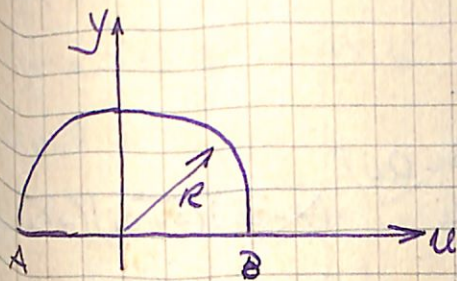
Dr. Curuti.

Calcular - $I = \int_{-\infty}^{+\infty} \frac{dx}{(x^2+a^2)(x^2+b^2)^2}$ $a > 0$
 $b > 0$

é integral generalizada.

Ora, $\int_{-\infty}^{+\infty} Q(x) dx = \int_{-\infty}^{+\infty} \frac{N(x)}{D(x)} dx$ os polos
devem ser complexos; o grau de D maior
que o de N.

Então - $I = 2\pi i \sum R(a_i^+)$



$\int_{\Omega} Q(z) dz = \int_{AB} Q(z) dz +$

$+\int_C Q(z) dz$

$\int_{-R}^R Q(u) du$

Quando $R \rightarrow \infty$ $\int_{\Omega} Q(z) dz = \int_{-\infty}^{+\infty} Q(u) du =$

$= 2\pi i \sum R(a_i^+)$

Não deve haver polo

real (sobre o eixo Ox) se houver polos
reais simples: -

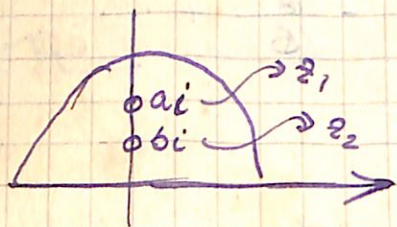
$\int_{-\infty}^{+\infty} Q(u) du = 2\pi i \sum R(a_i^+) + \pi i \sum R(a_{rs})$

Consideramos então -

$$Q(z) = \frac{1}{(z^2+a^2)(z^2+b^2)^2} \quad \text{os polos vemos que}$$

são - $z = \pm ai$ (simples) e $z = \pm bi$ (duplos)

do semi-plano superior são - $+ai$ e $+bi$



portanto, a integral se transforma em -

$$I = \int_{C+AB} \frac{dz}{(z^2+a^2)(z^2+b^2)^2} =$$

$= 2\pi i \sum R(a_s^+)$ aplicando o teorema -

$$I = \lim_{R \rightarrow \infty} \left[\int_{AB} \frac{dz}{(z^2+a^2)(z^2+b^2)^2} + \int_C \frac{dz}{(z^2+a^2)(z^2+b^2)^2} \right]$$

$$= \int_{-\infty}^{+\infty} \frac{dx}{(x^2+a^2)(x^2+b^2)^2} = 2\pi i \sum R(a_s^+)$$

Cálculo dos polos -

$$R(z_1) = R(ai) = \lim_{z \rightarrow ai} (z-ai) \frac{1}{(z-ai)(z+ai)(z^2+b^2)^2}$$

$$= \frac{1}{2ai(b^2-a^2)^2}$$

caso agora do polo duplo -

em geral, se o polo é de multiplicidade n

$$R(a) = \lim_{z \rightarrow a} \frac{D^{m-1}}{D} \frac{(z-a)^m f(z)}{(z-a)^{m-1}} \quad D = \frac{d}{dz}$$

$$R(bi) = \lim_{z \rightarrow bi} \left[\frac{d}{dz} \frac{(z-bi)^2}{(z^2+a^2)(z^2+b^2)^2} \right] \frac{1}{2!} =$$

$$R(bi) = \frac{i}{4} \frac{3b^2 - a^2}{b^3(a^2-b^2)^2}$$

$$I = 2\pi i \left[\frac{1}{2ai(b^2-a^2)} + \frac{i}{4} \frac{3b^2-a^2}{b^3(a^2-b^2)^2} \right] =$$

$$= \frac{\pi(a+2b)}{2ab^3(a+b)^2}$$

Calcular - $I = \int_0^{\pi} \frac{\cos 3u}{\cos u + 2} du$
a função é par, logo -

$$I = \frac{1}{2} \int_0^{2\pi} \frac{\cos 3u}{\cos u + 2} du \quad \text{para cairmos no caso do círculo unitário.}$$

$$\begin{aligned} \textcircled{1} e^{iu} &= \cos u + i \sin u \\ e^{i3u} &= \cos 3u + i \sin 3u = z^3 \end{aligned} \quad \left. \begin{aligned} du &= e^{iu} idu \\ du &= \frac{dz}{iz} \end{aligned} \right\}$$

$$\frac{1}{z} = \cos u - i \sin u \quad \frac{1}{z^3} = \cos 3u - i \sin 3u$$

$$\textcircled{1} + \textcircled{2} \rightarrow \left. \begin{aligned} \cos u &= \frac{1}{2} \left(z + \frac{1}{z} \right) \\ \cos 3u &= \frac{1}{2} \left(z^3 + \frac{1}{z^3} \right) \end{aligned} \right\} \text{suporta } p=1.$$

$$I = \frac{1}{2} \int_C \frac{\frac{1}{2} \left(z^3 + \frac{1}{z^3} \right)}{\frac{1}{2} \left(z + \frac{1}{z} \right) + 2} \cdot \frac{dz}{z}$$

na integral!

$$I = \frac{1}{2} \int_0^{2\pi} \frac{e^{i3x} - i \sin 3x}{\cos x + 2} dx = \frac{1}{2} \int_0^{2\pi} \frac{e^{i3x}}{\cos x + 2} - \frac{i}{2} \int_0^{2\pi} \frac{\sin 3x}{\cos x + 2} dx$$

$$+ f(u) = -f(-u) \quad \leftarrow \text{af. 0, par}$$

reduzimos o cálculo a -

$$I = \frac{1}{2} \int_0^{2\pi} \frac{e^{i3u} du}{\cos u + 2} \quad \text{passamos agora ao campo complexo; (circ. unitaris...)}$$

$$I = \frac{1}{2} \int_C \frac{z^3 dz}{i \left[\frac{1}{2} \left(z + \frac{1}{z} \right) + 2 \right]}$$

$$= \frac{i}{2} \int_C \frac{z^3 dz}{z^2 + 4z + 1} \quad \text{Determinação dos polos - } z = \begin{cases} -2 + \sqrt{3} < 1 \text{ (único p. int. rest.)} \\ -2 - \sqrt{3} > 1 \end{cases}$$

calculo do residuo

$$R(z_1) = \lim_{z \rightarrow z_1} \frac{(z - z_1) z^3}{(z - z_1)(z - z_2)} = \frac{-26 + 15\sqrt{3}}{2\sqrt{3}} \cdot 2i$$

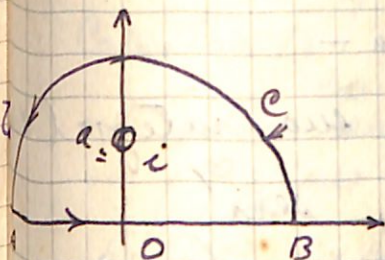
$$\text{portanto } I = -i \cdot 2\pi i \left(\frac{15 - 26\sqrt{3}}{2\sqrt{3}} \right)$$

$$= \pi \left(15 - \frac{26}{\sqrt{3}} \right)$$

FINIS.

$$\text{Calcular - } \int_{-\infty}^{+\infty} \frac{dx}{(x^2 + 1)^3} \quad \text{Vaj}$$

$$Q(z) = \frac{1}{(z^2 + 1)^3} \quad z = \pm i \text{ (tripla)}$$



$$\int_C Q(z) dz = 2\pi i \sum_s R(a_s)$$

$$\begin{aligned} \int_C Q(z) dz &= \int_{AB} Q(z) dz + \int_{BC} Q(z) dz = \\ &= \int_{-\infty}^{+\infty} Q(x) dx + \int_{\text{arc}} Q(z) dz \end{aligned}$$

quando $R \rightarrow \infty$

$$\int_C Q(z) dz = 0 + \int_{-\infty}^{+\infty} Q(x) dx$$

$$I = 2\pi i \sum R(a_s^+)$$

$$R(+i) = \lim_{z \rightarrow i} \frac{d^2}{dz^2} (z-i)^3 \cdot \frac{1}{(z^2+1)^3} \cdot \frac{1}{2!} =$$

$$= \lim_{z \rightarrow i} \frac{1}{2!} \frac{d^2}{dz^2} \frac{(z-i)^3}{(z+i)^3 (z-i)^3} =$$

$$\lim_{z \rightarrow i} \frac{12}{(z+i)^5} = \frac{3}{16i}$$

$$\text{Portanto } I = \frac{3\pi}{8}$$

lema de Jordan - Aplicações

$$I = \int_0^{+\infty} \frac{\cos ux}{a^2 + x^2} dx \quad \begin{cases} a > 0 \\ u > 0 \end{cases} \quad \text{a função, inte. grável e par,}$$

logo - $I = \frac{1}{2} \int_{-\infty}^{+\infty} \frac{\cos ux}{a^2 + x^2} dx$

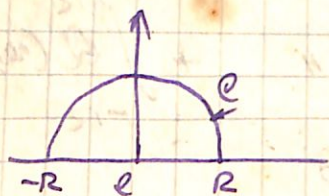
$$e^{imz} = \cos mz + i \sin mz$$

$$I = \frac{1}{2} \int_{-\infty}^{+\infty} \frac{e^{imx}}{a^2+x^2} dx - \int_{-\infty}^{+\infty} \frac{\sin mx}{a^2+x^2} dx$$

pois a função é ímpar.

Ora, pelo lema de Jordan -

se tivermos $e^{imz} f(z)$, sua integral ao longo do contorno $c+l$, será



$$\int_{c+l} e^{imz} f(z) dz = \int_c e^{imz} f(z) dz + \int_{l} e^{imz} f(z) dz$$

$$+ \int_{-R}^R e^{imx} f(x) dx$$

pois $R \rightarrow \infty$, diz o lema de Jordan -

$$\int_{c+l} e^{imz} f(z) dz = 0 + \int_{-\infty}^{+\infty} e^{imx} f(x) dx =$$

$$= 2\pi i \sum_s R(a_s^+)$$

havendo polos reais simples, acrescenta-se

$$\left[\pi i \sum_k \text{Res}(a_k) \right]$$

então, no caso -

$$I = \frac{1}{2} \int_{-\infty}^{+\infty} \frac{e^{imx}}{a^2+x^2} dx$$

$$a^2+z^2=0 \quad z = \pm ai \quad z' = ai$$

$$R = \lim_{z \rightarrow ai} (z - ai) \frac{e^{imz}}{a^2+z^2} = \frac{e^{-ma}}{2ai}$$

$$I = \frac{\pi e^{-ma}}{2a}$$

Calcular $I = \int_{-\infty}^{+\infty} \frac{\sin^k mx}{x^2(a^2+x^2)^2} dx$

há polos reais simples e polos complexos.

$$I = \frac{1}{i} \int_{-\infty}^{+\infty} \frac{e^{imx}}{x^2(a^2+x^2)^2} dx - \frac{1}{i} \int_{-\infty}^{+\infty} \frac{\cos mx}{x^2(a^2+x^2)^2} dx$$

integral ímpar e extremos simétricos

Consideramos -

$$Q(z) = \frac{e^{imz}}{z^2(a^2+z^2)^2} \quad z_1 = 0$$

$$z_2 = +ai \text{ (duplo)} \\ z_3 = -ai$$

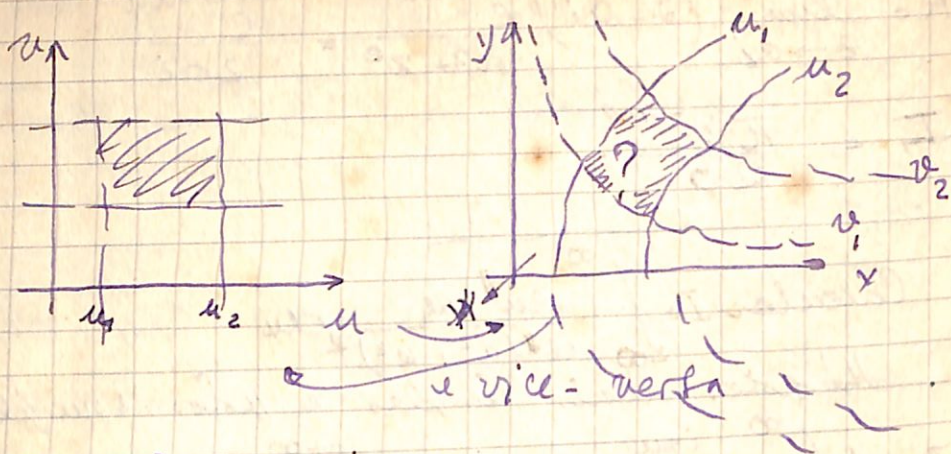
$$R(z_1) = \lim_{z \rightarrow 0} \frac{(z-0) e^{imz}}{z^2(a^2+z^2)^2} = \frac{1}{a^4}$$

$$R(z_2) = \lim_{z \rightarrow ai} \frac{d}{dz} \frac{(z-ai)^2 e^{imz}}{z^2(a^2+z^2)^2}$$

$$= \lim_{z \rightarrow ai} \frac{d}{dz} \frac{e^{imz}}{z(z+z_0)^2} \quad \text{faça}$$

Estudar a transformação -

$Z = f(z) = z^2$ e mostrar qual a figura transformada no plano u, v , de um retângulo no plano x, y , de Pergunta-se se a transformação é conforme.



$$\text{Ora, } \left. \begin{aligned} z &= u + iv \\ \bar{z} &= u - iy \end{aligned} \right\} \rightarrow$$

$$(u + iy)^2 = u + iv$$

$$u^2 - y^2 + 2iuy = u + iv$$

$$u = u^2 - y^2$$

$$v = 2uy$$

$$u^2 - y^2 = u_1 \quad (u_2) \rightarrow u^2 - y^2 = \text{cte}$$

$$2uy = v_1 \quad (v_2) \rightarrow 2uy = \text{cte (hiperbole equit.)}$$

Transformação inversa.

Faça!

Exercício - polinômios

a) $a \neq 0$ $L(y) = P_s(x)$

$$\bar{y} = a_n x^n + a_{n-1} x^{n-1} + \dots + a_0$$

b) $a_n = a_{n-1} = a_{n-2} = \dots = a_{n-m-1} = 0$ $a_{n-m} \neq 0$

$$X = P_s(x)$$

$$\bar{y} = x^m (a_0 x^0 + a_1 x^1 + \dots + a_s x^s)$$

São nec. m quadraturas.

c) O 2º membro de $L(y)$ é $X = P_s(x)$
 $y = z e^{ax}$ integral.

ASSUNTOS

Equações lineares de ordem

Teorema de invariância da diferencial -

$df = \frac{\partial f}{\partial u} du + \frac{\partial f}{\partial y} dy$ quer u e y sejam variáveis independentes, quer sejam funções de u e v .

Teorema de Euler - $u f'_u + y f'_y + \dots = n f(u, y, z, \dots)$

Equações diferenciais -

Ef. dif. lineares - $X_0 y^{(n)} + X_1 y^{(n-1)} + \dots + X_n y = X$

Teorema de Lagrange - a sol. de uma equação linear completa fica reduzida ao conhecimento do sistema fund. de soluções e de n quadraturas.

Teorema - e^{rx} é solução $L(y) = 0$ se r for raiz não nula da equação caract. $\sum a_{n-i} r^i = 0$

